# Operating Instructions

**Radar sensor for continuous level measurement of bulk solids**

## VEGAPULS 68

Profibus PA

Document ID: 36537

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**Safety instructions for Ex areas**

Please note the Ex-specific safety information for installation and operation in Ex areas. These safety instructions are part of the operating instructions manual and come with the Ex-approved instruments.

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# 1 About this document

## 1.1 Function

This operating instructions manual provides all the information you need for mounting, connection and setup as well as important instructions for maintenance and fault rectification. Please read this information before putting the instrument into operation and keep this manual accessible in the immediate vicinity of the device.

## 1.2 Target group

This operating instructions manual is directed to trained specialist personnel. The contents of this manual should be made available to these personnel and put into practice by them.

## 1.3 Symbolism used

**Information, tip, note**
This symbol indicates helpful additional information.

**Caution:** If this warning is ignored, faults or malfunctions can result.

**Warning:** If this warning is ignored, injury to persons and/or serious damage to the instrument can result.

**Danger:** If this warning is ignored, serious injury to persons and/or destruction of the instrument can result.

**Ex applications**
This symbol indicates special instructions for Ex applications.

- **List**
  The dot set in front indicates a list with no implied sequence.

→ **Action**
This arrow indicates a single action.

1 **Sequence of actions**
Numbers set in front indicate successive steps in a procedure.

**Battery disposal**
This symbol indicates special information about the disposal of batteries and accumulators.

# 2 For your safety

## 2.1 Authorised personnel

All operations described in this operating instructions manual must be carried out only by trained specialist personnel authorised by the plant operator.

During work on and with the device the required personal protective equipment must always be worn.

## 2.2 Appropriate use

VEGAPULS 68 is a sensor for continuous level measurement.

You can find detailed information about the area of application in chapter "*Product description*".

Operational reliability is ensured only if the instrument is properly used according to the specifications in the operating instructions manual as well as possible supplementary instructions.

## 2.3 Warning about incorrect use

Inappropriate or incorrect use of the instrument can give rise to application-specific hazards, e.g. vessel overfill or damage to system components through incorrect mounting or adjustment.

## 2.4 General safety instructions

This is a state-of-the-art instrument complying with all prevailing regulations and guidelines. The instrument must only be operated in a technically flawless and reliable condition. The operator is responsible for the trouble-free operation of the instrument.

During the entire duration of use, the user is obliged to determine the compliance of the necessary occupational safety measures with the current valid rules and regulations and also take note of new regulations.

The safety instructions in this operating instructions manual, the national installation standards as well as the valid safety regulations and accident prevention rules must be observed by the user.

For safety and warranty reasons, any invasive work on the device beyond that described in the operating instructions manual may be carried out only by personnel authorised by the manufacturer. Arbitrary conversions or modifications are explicitly forbidden.

The safety approval markings and safety tips on the device must also be observed.

Depending on the instrument version, the emitting frequencies are in the C or K band range. The low emitting frequencies are far below the internationally approved limit values. When used correctly, there is no danger to health.

## 2.5 CE conformity

The device fulfills the legal requirements of the applicable EC guidelines. By affixing the CE marking, we confirm successful testing of the product.

You can find the CE Certificate of Conformity in the download section of our homepage.

**Electromagnetic compatibility**
Instruments in four-wire or Ex-d-ia version are designed for use in an industrial environment. Nevertheless, electromagnetic interference from electrical conductors and radiated emissions must be taken into account, as is usual with class A instruments according to EN 61326-1. If the instrument is used in a different environment, the electromagnetic compatibility to other instruments must be ensured by suitable measures.

## 2.6 NAMUR recommendations

NAMUR is the automation technology user association in the process industry in Germany. The published NAMUR recommendations are accepted as the standard in field instrumentation.

The device fulfills the requirements of the following NAMUR recommendations:

- NE 21 – Electromagnetic compatibility of equipment
- NE 43 – Signal level for malfunction information from measuring transducers
- NE 53 – Compatibility of field devices and display/adjustment components
- NE 107 – Self-monitoring and diagnosis of field devices

For further information see www.namur.de.

## 2.7 Radio license for Europe

The instrument is approved according to EN 302372-1/2 (2006-04) for use in closed vessels.

## 2.8 Radio license for USA/Canada

The instrument is in conformity with part 15 of the FCC regulations. Take note of the following two regulations:

- The instrument must not cause any interfering emissions
- The device must be insensitive to interfering immissions, including those that may cause undesirable operating conditions

Modifications not expressly approved by the manufacturer will lead to expiry of the operating licence according to FCC/IC.

The instrument is in conformity with RSS-210 of the IC regulations.

The instrument may only be used in closed vessels made of metal, concrete, or fibre-reinforced plastic.

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## 2.9 Environmental instructions

Protection of the environment is one of our most important duties. That is why we have introduced an environment management system with the goal of continuously improving company environmental protection. The environment management system is certified according to DIN EN ISO 14001.

Please help us fulfill this obligation by observing the environmental instructions in this manual:

- Chapter "*Packaging, transport and storage*"
- Chapter "*Disposal*"

# 3 Product description

## 3.1 Configuration

**Type label**

The type label contains the most important data for identification and use of the instrument:

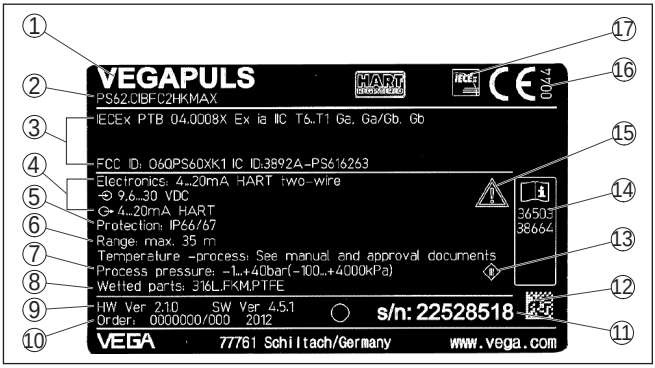


*Fig. 1: Layout of the type label (example)*

1 *Instrument type*
2 *Product code*
3 *Approvals*
4 *Power supply and signal output, electronics*
5 *Protection rating*
6 *Measuring range*
7 *Process and ambient temperature, process pressure*
8 *Material, wetted parts*
9 *Hardware and software version*
10 *Order number*
11 *Serial number of the instrument*
12 *Data-Matrix-Code for Smartphone-App*
13 *Symbol of the device protection class*
14 *ID numbers, instrument documentation*
15 *Reminder to observe the instrument documentation*
16 *Notified authority for CE marking*
17 *Approval directive*

**Serial number - Instrument search**

The type label contains the serial number of the instrument. With it you can find the following instrument data on our homepage:

- Product code (HTML)
- Delivery date (HTML)
- Order-specific instrument features (HTML)
- Operating instructions and quick setup guide at the time of shipment (PDF)
- Order-specific sensor data for an electronics exchange (XML)
- Test certificate (PDF) - optional

Go to www.vega.com, "*VEGA Tools*" and "*Instrument search*". Enter the serial number.

Alternatively, you can access the data via your smartphone:

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- Download the smartphone app "*VEGA Tools*" from the "*Apple App Store*" or the "*Google Play Store*"
- Scan the Data Matrix code on the type label of the instrument or
- Enter the serial number manually in the app

**Scope of this operating instructions manual**

This operating instructions manual applies to the following instrument versions:

- Hardware from 2.1.1
- Software from 4.5.0

**Scope of delivery**

The scope of delivery encompasses:

- Radar sensor
- Documentation
  - Quick setup guide VEGAPULS 68
  - Test certificate Measurement accuracy, depending on the instrument VEGAPULS 68 (optional)
  - Operating instructions manual "*DIsplay and adjustment module PLICSCOM*" (optional)
  - Supplementary instructions "*GSM/GPRS radio module*" (optional)
  - Supplementary instructions manual "*Heating for display and adjustment module*" (optional)
  - Supplementary instructions manual "*Plug connector for continuously measuring sensors*" (optional)
  - Ex-specific "*Safety instructions*" (with Ex versions)
  - if necessary, further certificates
- DVD "*Software & Documents*", containing
  - Operating instructions
  - Safety instructions
  - PACTware/DTM-Collection
  - Driver software

## 3.2 Principle of operation

**Application area**

The VEGAPULS 68 is a radar sensor for continuous measurement of bulk solids also under arduous process conditions and large measuring ranges. It the ideal solution for level measurement in high silos, large bunkers, stone crushers and melting furnaces. With different antenna versions and materials, this sensor is the optimum solution for virtually all applications and processes.

The instrument is also suitable for applications in liquids.

Dependent on the application range, different versions are used:

- Small silos and vessels, measurement of virtually all bulk solids: **Horn antenna**
- Large silos and vessels, measurement of bulk solids with low $\varepsilon_r$ value: **Parabolic antenna**
- Liquids: **Parabolic antenna**

The instrument can be used with products with an $\varepsilon_r$ value ≥1.5. The actually achievable value depends on the measuring conditions and the antenna system.

**Functional principle**

The antenna of the radar sensor emits short radar pulses with a duration of approx. 1 ns. These pulses are reflected by the product and received by the antenna as echoes. The transit time of the radar pulses from emission to reception is proportional to the distance and hence to the level. The determined level is converted into an appropriate output signal and outputted as measured value.

## 3.3 Packaging, transport and storage

**Packaging**

Your instrument was protected by packaging during transport. Its capacity to handle normal loads during transport is assured by a test based on ISO 4180.

The packaging of standard instruments consists of environment-friendly, recyclable cardboard. For special versions, PE foam or PE foil is also used. Dispose of the packaging material via specialised recycling companies.

**Transport**

Transport must be carried out in due consideration of the notes on the transport packaging. Nonobservance of these instructions can cause damage to the device.

**Transport inspection**

The delivery must be checked for completeness and possible transit damage immediately at receipt. Ascertained transit damage or concealed defects must be appropriately dealt with.

**Storage**

Up to the time of installation, the packages must be left closed and stored according to the orientation and storage markings on the outside.

Unless otherwise indicated, the packages must be stored only under the following conditions:

- Not in the open
- Dry and dust free
- Not exposed to corrosive media
- Protected against solar radiation
- Avoiding mechanical shock and vibration

**Storage and transport temperature**

- Storage and transport temperature see chapter "*Supplement - Technical data - Ambient conditions*"
- Relative humidity 20 … 85 %

## 3.4 Accessories and replacement parts

**PLICSCOM**

The display and adjustment module PLICSCOM is used for measured value indication, adjustment and diagnosis. It can be inserted into the sensor or the external display and adjustment unit and removed at any time.

You can find further information in the operating instructions "*Display and adjustment module PLICSCOM*" (Document-ID 27835).

**VEGACONNECT**

The interface adapter VEGACONNECT enables the connection of communication-capable instruments to the USB interface of a PC. For

parameter adjustment of these instruments, the adjustment software PACTware with VEGA-DTM is required.

You can find further information in the operating instructions "*Interface adapter VEGACONNECT*" (Document-ID 32628).

**VEGADIS 81**

The VEGADIS 81 is an external display and adjustment unit for VEGA plics® sensors.

For sensors with double chamber housing the interface adapter "*DIS-ADAPT*" is also required for VEGADIS 81.

You can find further information in the operating instructions "*VEGADIS 81*" (Document-ID 43814).

**DIS-ADAPT**

The adapter "*DIS-ADAPT*" is an accessory part for sensors with double chamber housings. It enables the connection of VEGADIS 81 to the sensor housing via an M12 x 1 plug.

You can find further information in the supplementary instructions "*Adapter DISADAPT*" (Document-ID 45250).

**PLICSMOBILE T61**

The PLICSMOBILE T61 is an external GSM/GPRS radio unit for transmission of measured values and for remote parameter adjustment of plics® sensors. The adjustment is carried out via PACTware/DTM by using the integrated USB connection.

You can find further information in the supplementary instructions "*PLICSMOBILE T61*" (Document-ID 37700).

**PLICSMOBILE**

The PLICSMOBILE is an internal GSM/GPRS radio unit for transmission of measured values and for remote parameter adjustment of plics® sensors. The adjustment is carried out via PACTware/DTM by using the integrated USB connection.

You can find further information in the supplementary instructions "*PLICSMOBILE GSM/GPRS radio module*" (Document-ID 36849).

**Flanges**

Screwed flanges are available in different versions according to the following standards: DIN 2501, EN 1092-1, BS 10, ANSI B 16.5, JIS B 2210-1984, GOST 12821-80.

You can find additional information in the supplementary instructions manual "*Flanges according to DIN-EN-ASME-JIS*" (Document-ID 31088).

**Protective cap**

The protective cover protects the sensor housing against soiling and intense heat from solar radiation.

You will find additional information in the supplementary instructions manual "*Protective cover*" (Document-ID 34296).

**Electronics module**

The electronics module VEGAPULS series 60 is a replacement part for radar sensors of VEGAPULS series 60. There is a different version available for each type of signal output.

You can find further information in the operating instructions "*Electronics module VEGAPULS series 60*" (Document-ID 36801).

**Supplementary electronics Profibus PA**

The supplementary is a replacement part for the following sensors with signal output Profibus PA:

- VEGAPULS series 60
- VEGAFLEX 80 series
- VEGABAR series 80

You can find further information in the operating instructions "*Supplementary electronics for Profibus PA*" (Document-ID 42767).

**Antenna impedance cone**

The antenna impedance cone is a replacement part used for optimum transmission of microwaves and for sealing against the process.

You find further information in the operating instructions "*Antenna impedance cone VEGAPULS 62 and 68*" (Document-ID 31381).

# 4 Mounting

## 4.1 General instructions

**Screwing in**

On instruments with process fitting thread, the hexagon must be tightened with a suitable screwdriver. Wrench size see chapter "*Dimensions*".

**Warning:**
The housing must not be used to screw the instrument in! Applying tightening force can damage internal parts of the housing.

**Protection against moisture**

Protect your instrument against moisture penetration through the following measures:

- Use the recommended cable (see chapter "*Connecting to power supply*")
- Tighten the cable gland
- Turn the housing in such a way that the cable gland points downward
- Loop the connection cable downward in front of the cable gland

This applies particularly to:

- Outdoor mounting
- Installations in areas where high humidity is expected (e.g. through cleaning processes)
- Installations on cooled or heated vessels

**Suitability for the process conditions**

Make sure that all parts of the instrument exposed to the process are suitable for the existing process conditions.

These are mainly:

- Active measuring component
- Process fitting
- Process seal

Process conditions are particularly:

- Process pressure
- Process temperature
- Chemical properties of the medium
- Abrasion and mechanical influences

You can find the specifications of the process conditions in chapter "*Technical data*" as well as on the type label.

## 4.2 Mounting preparations - Horn antenna

The instrument is also available in versions with an antenna whose diameter is larger than the process fitting (thread, flange). In such cases the antenna must be disconnected from the process fitting before mounting. Proceed as follows:

1. Loosen the hexagon socket screws (3) on the antenna socket with an Allen wrench (size 3)
2. Remove the antenna (4)

**Note:**
The plastic cone may not be pulled out of the antenna socket.

3. Insert the antenna from below into the vessel socket and secure it against falling off
4. Retighten the antenna with hexagon screws to the antenna socket; torque max. 2.5 Nm (1.8 lbf ft)

**Note:**
The radar sensor with rinsing air connection or antenna extension is provided with a notch on the antenna socket. This notch must be aligned with the marking on the process fitting (the marking specifies the position of the polarisation of the radar signal).

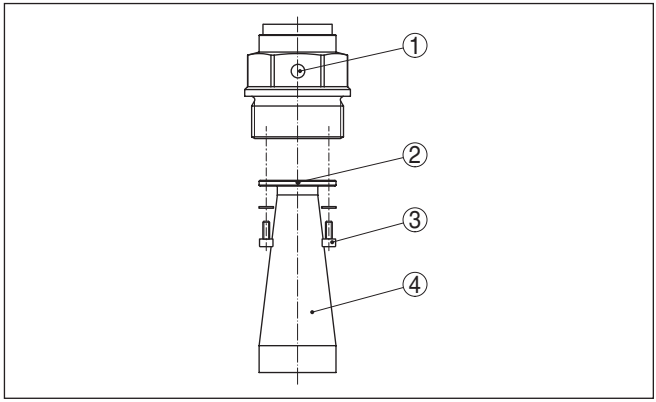


*Fig. 2: Dismounting of the horn antenna*

*1 Marking for the polarisation*
*2 Marking at the antenna socket*
*3 Hexagon screws on the antenna socket*
*4 Antenna*

## 4.3 Mounting preparations - Parabolic antenna

The instrument is also available in versions where the antenna has a diameter larger than the process fitting (thread, flange). With such versions the antenna must be disconnected from the process fitting before mounting. Proceed as follows:

1. Clamp VEGAPULS 68 with the flange, e.g. in a bench vice
2. Hold the connection piece (1) with a wrench on the flat surfaces (width across flats 22 mm)
3. Loosen counter nut (3) completely with a wrench (width across flats 36 mm) in the direction of the antenna
4. Loosen compression nut (2) completely with a wrench (width across flats 41 mm) in the direction of the antenna
5. Remove the parabolic antenna (4) axially
6. Mount sensor flange on the adapter flange and fasten it tightly
7. Check if the O-ring seal is present on the connection piece and make sure it is not damaged.

**Note:**
A damaged O-ring seal must be replaced: FKM (SHS FPM 70C3 GLT), FFKM (Kalrez 6375)

8. Remount the parabolic antenna (4)
9. Fasten compression nut (2) with a wrench (width across flats 41), torque max. 50 Nm
10. Fasten counter nut (3) with a wrench (width across flats 36), torque max. 40 Nm

**Note:**
On the version with rinsing air connection, make sure that the holes in the antenna and in the process fitting coincide. This ensures a sufficient air flow (the air is led through the holes to the feed system. A rinsing of the whole parabolic antenna is not intended).

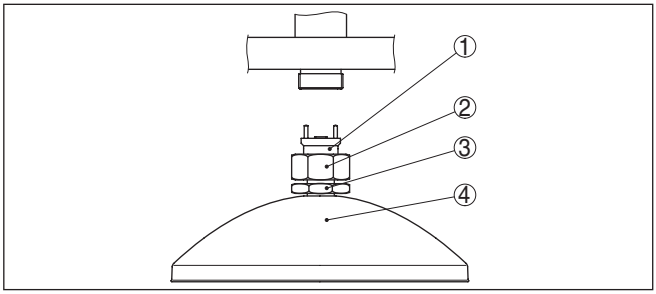


*Fig. 3: Dismounting, parabolic antenna*

*1 Connection piece*
*2 Compression nut*
*3 Locknut*
*4 Parabolic antenna*

## 4.4 Mounting instructions

**Horn and parabolic antenna**

The illustrations with the following mounting instructions show a radar sensor with horn antenna. The mounting instructions apply analogously also to the version with parabolic antenna.

**Polarisation**

The emitted radar impulses of the radar sensor are electromagnetic waves. The polarisation is the direction of the electrical wave component. By turning the instrument in the connection flange or mounting boss, the polarisation can be used to reduce the effects of false echoes.

The position of the polarisation is marked on the process fitting of the instrument.

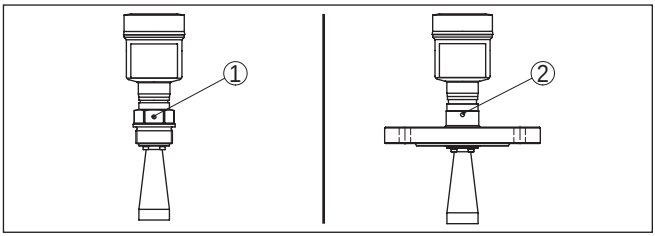


*Fig. 4: Position of the polarisation*

*1 Marking with screwed version*
*2 Marking with flange version*

**Installation position**

Mount the sensor at least 200 mm (7.874 in) away from the vessel wall.

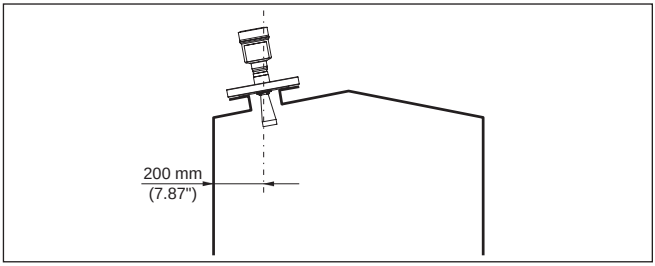


*Fig. 5: Mounting of the radar sensor on the vessel top*

If you cannot maintain this distance, you should carry out a false signal storage during setup. This applies particularly if buildup on the vessel wall is expected. In such a case, it is recommended to repeat the false signal storage at a later date with existing buildup.

**Inflowing medium**

Mounting should not be too close to the inflowing material as the microwave signal will be interferred. The optimum mounting position is on the opposite of the filling. To avoid strong pollution, the distance to the filter or dust extraction must be as big as possible.

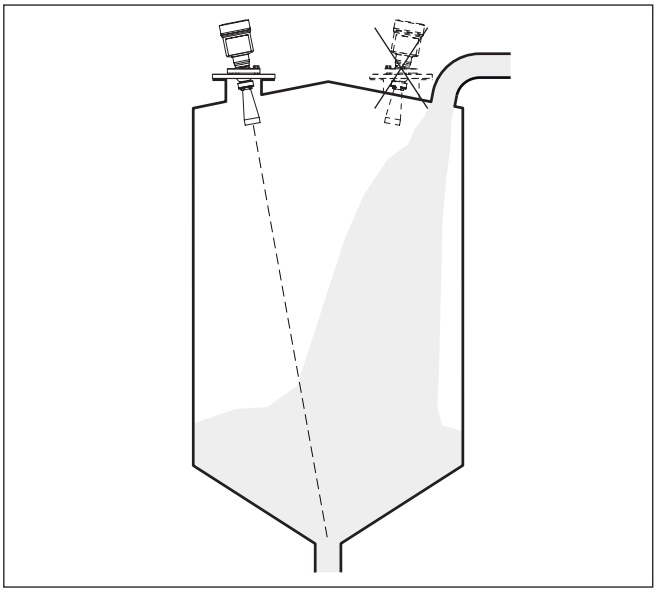

*Fig. 6: Mounting of the radar sensor with inflowing medium*

With bulk solids silos with lateral pneumatic filling, mounting should not be in the filling stream as the microwave signal will be interferred. The optimum mounting position is next to the filling. To avoid strong pollution, the distance to the filter or dust extraction must be as big as possible.

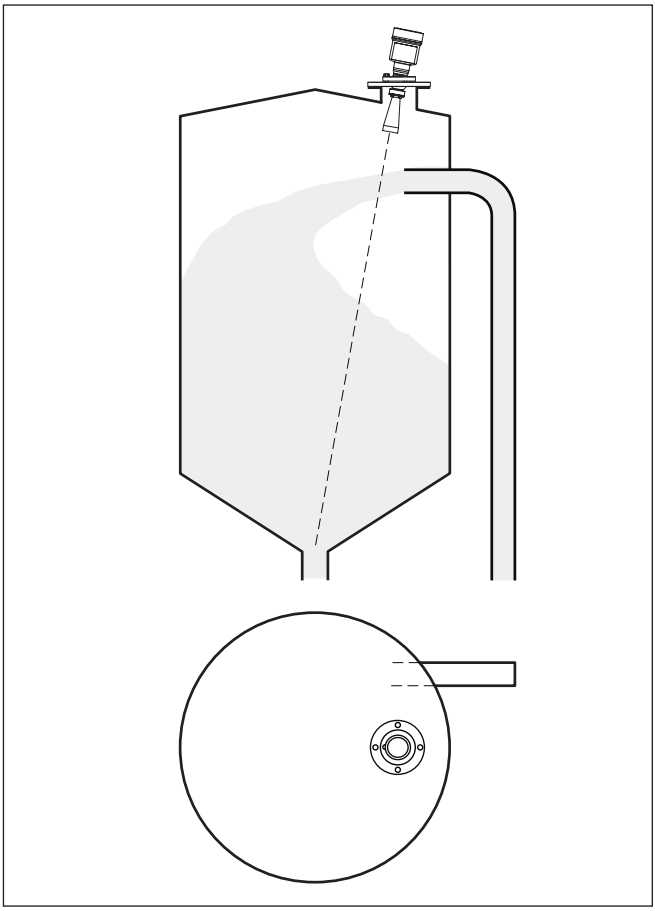

*Fig. 7: Mounting of the radar sensor with inflowing medium*

**Socket**

The socket piece should be dimensioned in such a way that the antenna end protrudes slightly out of the socket.

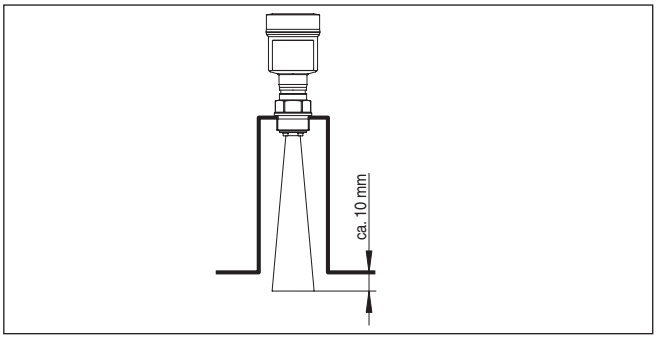


*Fig. 8: Recommended socket mounting with horn antenna*

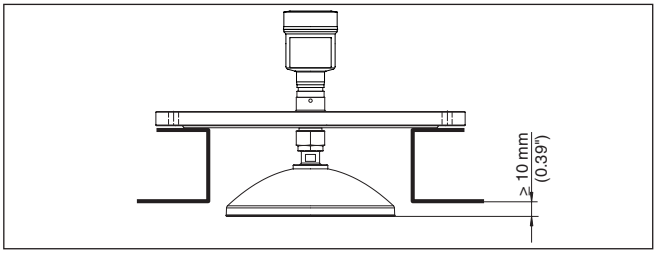


*Fig. 9: Recommended socket mounting with parabolic antenna*

When using a swivelling holder, keep in mind that the distance between antenna and socket gets smaller as the inclination of the sensor increases. Additional false reflections may be generated which can influence the measuring result at close range.

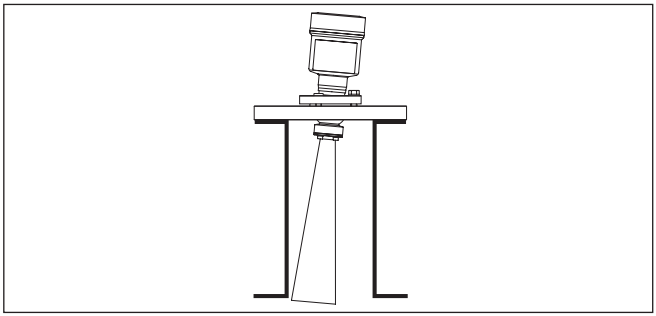

*Fig. 10: Distance between antenna and socket with horn antenna*

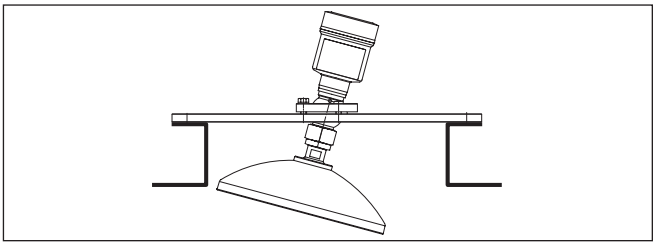

*Fig. 11: Distance between antenna and socket with parabolic antenna*

If the medium has good reflective properties, VEGAPULS 68 with horn antenna can also be mounted on a longer socket piece. Recommended values for socket heights are specified in the following illustration. You must carry out a false echo storage afterwards.

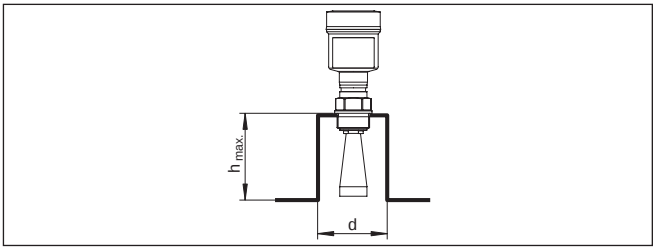


*Fig. 12: Deviating socket dimensions*

| Socket diameter d | Socket length h | Recommended antenna diameter |
|---|---|---|
| 40 mm | ≤ 100 mm | 40 mm |
| 50 mm | ≤ 150 mm | 48 mm |
| 80 mm | ≤ 250 mm | 75 mm |
| 100 mm | ≤ 500 mm | 95 mm |
| 150 mm | ≤ 800 mm | 95 mm |

| Socket diameter d | Socket length h | Recommended antenna diameter |
|---|---|---|
| 1½" | ≤ 3.9 in | 1½" |
| 2" | ≤ 5.9 in | 2" |
| 3" | ≤ 9.8 in | 3" |
| 4" | ≤ 19.7 in | 4" |
| 6" | ≤ 31.5 in | 4" |

**Tip:**
The instrument is also optionally available with an antenna extension. The antenna length can be selected (either ex works or later) to allow the antenna to protrude slightly out of the end of the mounting socket. Due to the antenna extension however, disturbing reflections are generated in the close-up range. This can lead to an increase in the

required minimum distance, especially with poorly reflecting media such as plastic powder. In practice, a cleanly constructed mounting socket, if necessary with rounded edges, introduces fewer disturbing influences than an antenna extension.

**Orientation**

To measure as much of the vessel volume as possible, the sensor should be aligned so that the measuring beam reaches the lowest level in the vessel. In a cylindrical silo with conical outlet mounting is carried out on a socket. It should be positioned on one third up to the half of the vessel radius.

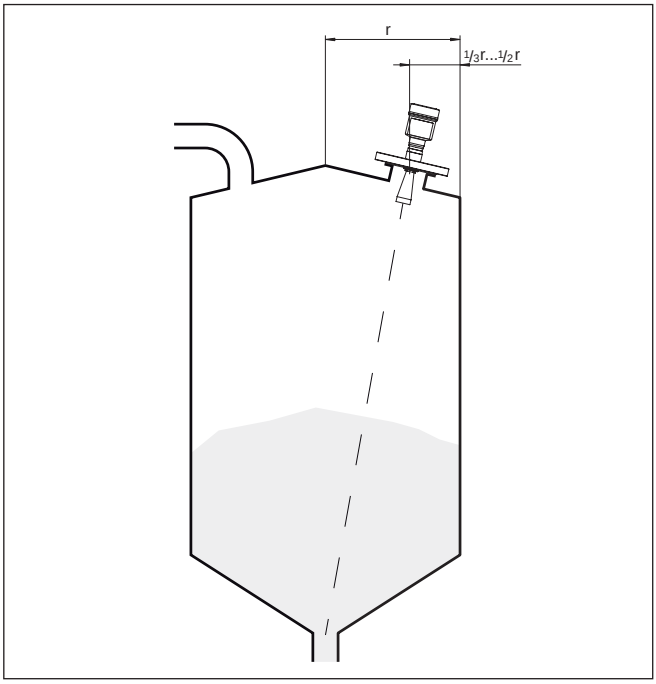


*Fig. 13: Orientation*

If mounting in the centre of the silo is not possible, the sensor can be directed to the vessel center by using the optional swivelling holder. The following description shows a simple way to determine the required angle of inclination.

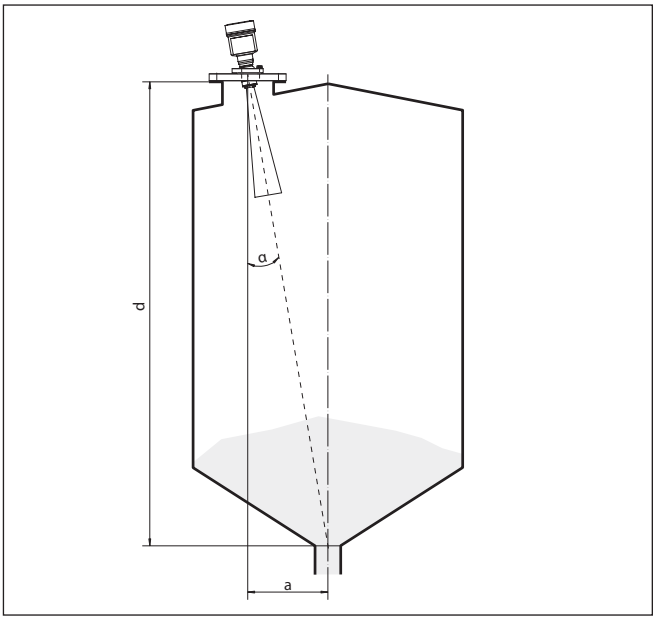


*Fig. 14: Proposal for installation after orientation VEGAPULS 68*

The angle of inclination depends on the vessel dimensions. It can be easily checked with a suitable level or water leve on the sensor.

The following chart specifies the distance "a" between installation position and vessel centre dependent on the measuring distance for inclination angles of 2° … 10°.

| Distance d (m) | 2° | 4° | 6° | 8° | 10° |
|---|---|---|---|---|---|
| 2 | 0.1 | 0.1 | 0.2 | 0.3 | 0.4 |
| 4 | 0.1 | 0.3 | 0.4 | 0.6 | 0.7 |
| 6 | 0.2 | 0.4 | 0.6 | 0.8 | 1.1 |
| 8 | 0.3 | 0.6 | 0.8 | 1.1 | 1.4 |
| 10 | 0.3 | 0.7 | 1.1 | 1.4 | 1.8 |
| 15 | 0.5 | 1.0 | 1.6 | 2.1 | 2.6 |
| 20 | 0.7 | 1.4 | 2.1 | 2.8 | 3.5 |
| 25 | 0.9 | 1.7 | 2.6 | 3.5 | 4.4 |
| 30 | 1.0 | 2.1 | 3.2 | 4.2 | 5.3 |
| 35 | 1.2 | 2.4 | 3.7 | 4.9 | 6.2 |
| 40 | 1.4 | 2.8 | 4.2 | 5.6 | 7.1 |
| 45 | 1.6 | 3.1 | 4.7 | 6.3 | 7.9 |
| 50 | 1.7 | 3.5 | 5.3 | 7 | 8.8 |

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| Distance d (m) | 2° | 4° | 6° | 8° | 10° |
|---|---|---|---|---|---|
| 55 | 1.9 | 3.8 | 5.8 | 7.7 | 9.7 |
| 60 | 2.1 | 4.2 | 6.3 | 8.4 | 10.6 |
| 65 | 2.3 | 4.5 | 6.8 | 9.1 | 11.5 |
| 70 | 2.4 | 4.9 | 7.4 | 9.8 | 12.3 |
| 75 | 2.6 | 5.2 | 7.9 | 1.0 | 13 |

Example:

In a vessel 20 m high, the installation position of the sensor is 1.4 m from the vessel centre.

The necessary angle of inclination of 4° can be read out from this chart.

Proceed as follows to adjust the angle of inclination with the swivelling holder:

1. Loosen terminal screw of the swivelling holder with a fork spanner SW 13
2. Direct the sensor, check angle of inclination

**Information:**
The max. angle of inclination of the swivelling holder is approx. 15°

3. Tighten the terminal screw, torque max. 20 Nm.

**Information:**
The hexagon screws must not be loosened.

**Vessel installations**

The mounting location of the radar sensor should be a place where no other equipment or fixtures cross the path of the microwave signals.

Vessel installations, such as e.g. ladders, limit switches, heating spirals, struts, etc., can cause false echoes and impair the useful echo. Make sure when planning your measuring site that the radar sensor has a "clear view" to the measured product.

In case of existing vessel installations, a false echo storage should be carried out during setup.

If large vessel installations such as struts or supports cause false echoes, these can be attenuated through supplementary measures. Small, inclined sheet metal baffles above the installations scatter the radar signals and prevent direct interfering reflections.

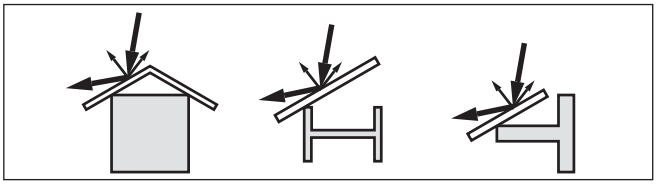

*Fig. 15: Cover smooth profiles with deflectors*

**Agitators**

If there are agitators in the vessel, a false signal suppression should be carried out with the agitators in motion. This ensures that the

interfering reflections from the agitators are saved with the blades in different positions.

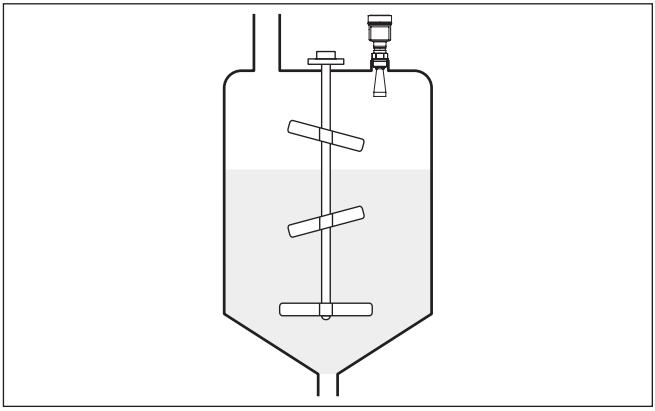

*Fig. 16: Agitators*

**Material heaps**

Large material heaps are detected with several sensors, which can be mounted on e.g. traverse cranes. For this type of application, it is best to orient the sensor toward the solid surface. A mutual infuence of the sensors is not possible.

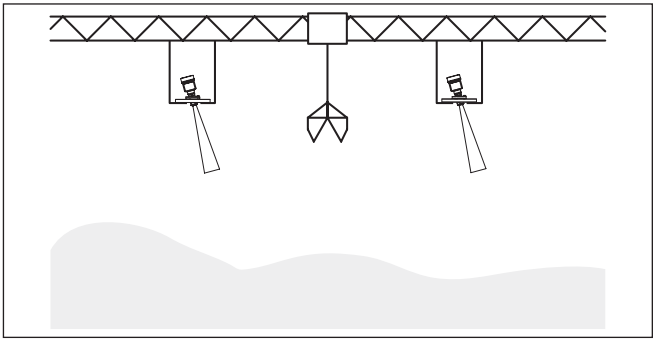

*Fig. 17: Radar sensors on traverse crane*

**Information:**
Keep in mind that for these applications, the sensors are designed for relatively slow level changes. When using VEGAPULS 68 on a movable bracket, the max. measuring rate must be observed (see chapter "*Technical data*").

**Mounting in the vessel insulation**

Instruments for a temperature range up to 250 °C or up to 450 °C have a distance piece between process fitting and electronics housing. Ths distance piece is used for thermal decoupling of the electronics against high process temperatures.

**Information:**
The distance piece must only be incorporated up to max. 50 mm in the vessel isolation. Only then, a reliable temperature decoupling is guaranteed.

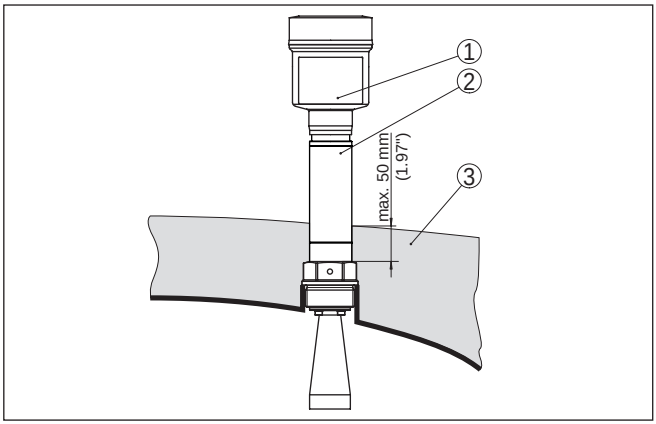


*Fig. 18: Mounting the instrument on insulated vessels.*

*1 Electronics housing*
*2 Distance piece*
*3 Vessel insulation*

**Installation in subsurface enclosures**

For level measurements in concrete silos, the sensors are often mounted in protective boxes. These boxes can be for example metallic, closed subsurface enclosures.

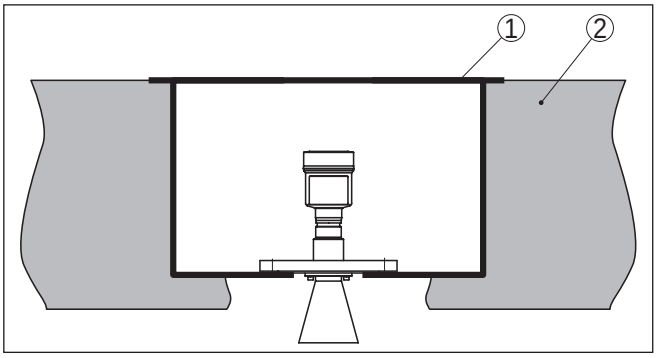


*Fig. 19: Mounting of the instrument in an subsurface enclosure*

*1 Subsurface enclosure*
*2 Concrete bottom*

For this application, the minimal amounts of stray radiation from the sensor can be reflected and strengthened by the walls of the subsurface enclosures. In the case of sensors with plastic housings, this can lead to coupling disturbances. This can be avoided by using a sensor with aluminium or stainless steel housing.

**Mounting in multiple chamber silo**

The silo walls of multiple chamber silos are often made of profile walls, such as e.g. profile sheeting, to ensure the required stability. If the radar sensor is mounted very close to a heavily structured vessel wall, considerable false reflections can be generated. Hence the sensor should be mounted at a large distance from the separating wall. The optimal mounting position is on the outer wall of the silo with the sensor directed towards the emptying aperture in the silo center.

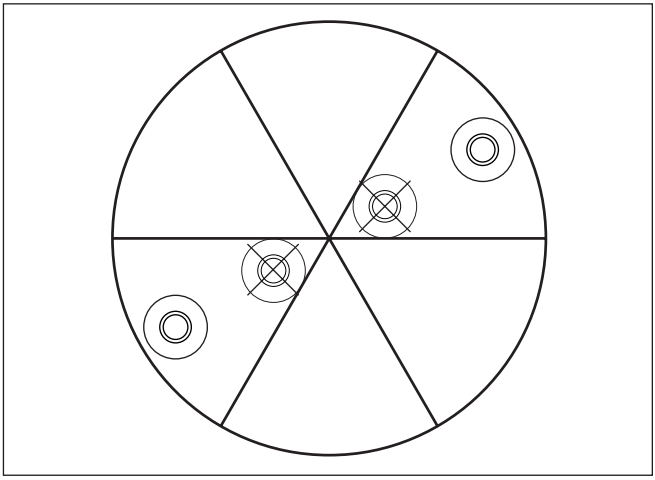

*Fig. 20: Mounting of VEGAPULS 68 in multiple chamber silos*

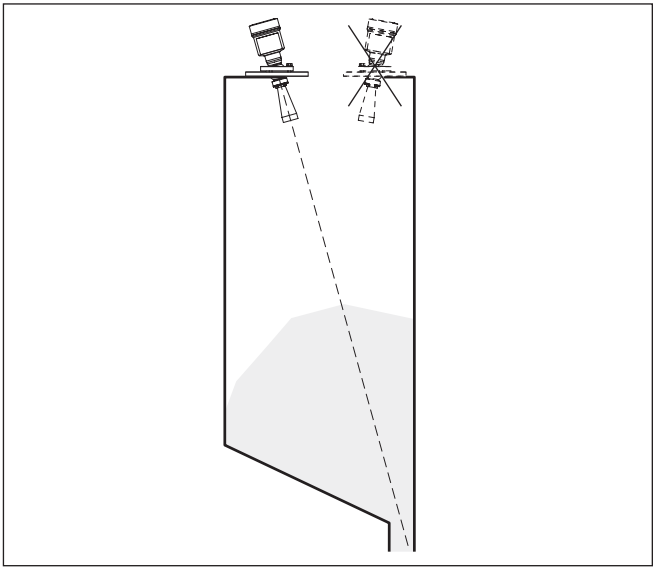

*Fig. 21: Orientation of VEGAPULS 68 for emptying in the silo center*

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**Dust layers**

To avoid strong buildup and dust in the antenna system, the sensor should not be mounted directly at the dust extraction of the vessel.

In case of extreme dust deposits in the antenna system, VEGAPULS 68 is available with a rinsing air connection. The air is distributed via channels in the antenna system and keeps it largely free of dust.

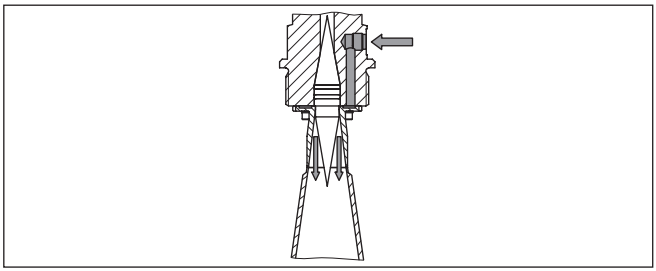

*Fig. 22: Purging air connection with horn antenna*

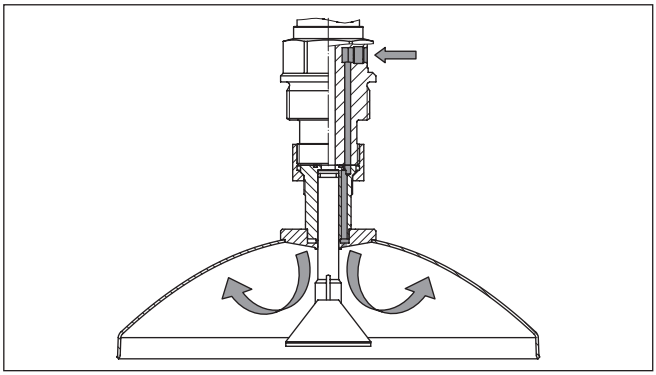

*Fig. 23: Purging air connection with parabolic antenna*

The practice has shown that a pressure of approx. 0.2 … 1 bar provides a sufficient air flow (see diagram in chapter "*Technical data*", "*Purging air connection*".

# 5 Connecting to the bus system

## 5.1 Preparing the connection

**Safety instructions**

Always keep in mind the following safety instructions:

- Connect only in the complete absence of line voltage
- If overvoltage surges are expected, overvoltage arresters should be installed

**Voltage supply**

The voltage supply is provided by a Profibus DP /PA segment coupler.

The voltage supply range can differ depending on the instrument version. You can find the data for voltage supply in chapter "*Technical data*".

**Connection cable**

Connection is made with screened cable according to the Profibus specification. Power supply and digital bus signal are carried over the same two-wire connection cable.

Use cable with round cross-section. A cable outer diameter of 5 … 9 mm (0.2 … 0.35 in) ensures the seal effect of the cable gland. If you are using cable with a different diameter or cross-section, exchange the seal or use a suitable cable gland.

Please make sure that your installation is carried out according to the Profibus specification. In particular, make sure that the termination of the bus is done with appropriate terminating resistors.

You can find detailed information of the cable specification, installation and topology in the "*Profibus PA - User and Installation Guideline*" on www.profibus.com.

**Cable gland ½ NPT**

With plastic housing, the NPT cable gland or the Conduit steel tube must be screwed without grease into the threaded insert.

Max. torque for all housings see chapter "*Technical data*".

**Cable screening and grounding**

Make sure that the cable screening and ground is executed according to the Fielbus specification. If electromagnetic interference is expected which is above the test values of EN 61326-1 for industrial areas, we recommend to connect the cable screen on both ends to ground potential.

In systems with potential equalisation, connect the cable screen directly to ground potential at the power supply unit, in the connection box and at the sensor. The screen in the sensor must be connected directly to the internal ground terminal. The ground terminal outside on the housing must be connected to the potential equalisation (low impedance).

In systems without potential equalisation with cable screening on both sides, connect the cable screen directly to ground potential at the power supply unit and at the sensor. In the connection box or T-distributor, the screen of the short stub to the sensor must not be connected to ground potential or to another cable screen. The cable screens to the power supply unit and to the next distributor must be connected to each other and also connected to ground potential via a

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ceramic capacitor (e.g. 1 nF, 1500 V). Low-frequency potential equalisation currents are thus suppressed, but the protective effect against high frequency interference signals remains.

## 5.2 Connecting

**Connection technology**

The voltage supply and signal output are connected via the spring-loaded terminals in the housing.

Connection to the display and adjustment module or to the interface adapter is carried out via contact pins in the housing.

**Information:**
The terminal block is pluggable and can be removed from the electronics. To do this, lift the terminal block with a small screwdriver and pull it out. When reinserting the terminal block, you should hear it snap in.

**Connection procedure**

Proceed as follows:

1. Unscrew the housing cover
2. If a display and adjustment module is installed, remove it by turning it slightly to the left.
3. Loosen compression nut of the cable entry gland
4. Remove approx. 10 cm (4 in) of the cable mantle, strip approx. 1 cm (0.4 in) of insulation from the ends of the individual wires
5. Insert the cable into the sensor through the cable entry

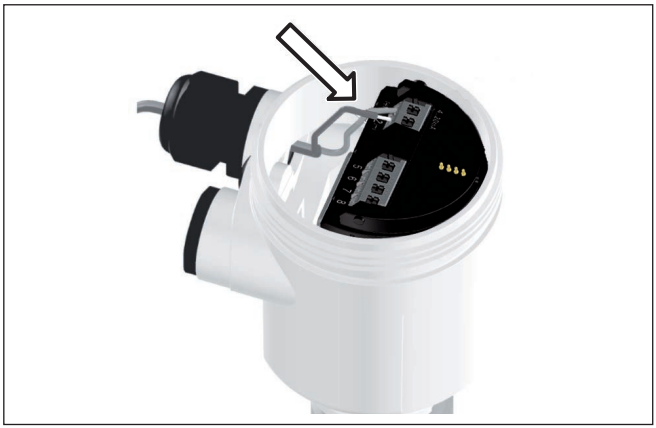


*Fig. 24: Connection steps 5 and 6 - Single chamber housing*

*Fig. 25: Connection steps 5 and 6 - Double chamber housing*

6. Insert the wire ends into the terminals according to the wiring plan

**Information:**
Solid cores as well as flexible cores with wire end sleeves are inserted directly into the terminal openings. In case of flexible cores without end sleeves, press the terminal from above with a small screwdriver, the terminal opening is then free. When the screwdriver is released, the terminal closes again.

You can find further information on the max. wire cross-section under "*Technical data/Electromechanical data*"

7. Check the hold of the wires in the terminals by lightly pulling on them
8. Connect the screen to the internal ground terminal, connect the outer ground terminal to potential equalisation
9. Tighten the compression nut of the cable entry gland. The seal ring must completely encircle the cable
10. Reinsert the display and adjustment module, if one was installed
11. Screw the housing cover back on

The electrical connection is finished.

## 5.3 Wiring plan, single chamber housing

The following illustration applies to the non-Ex as well as to the Ex-ia version.

**Electronics and terminal compartment**

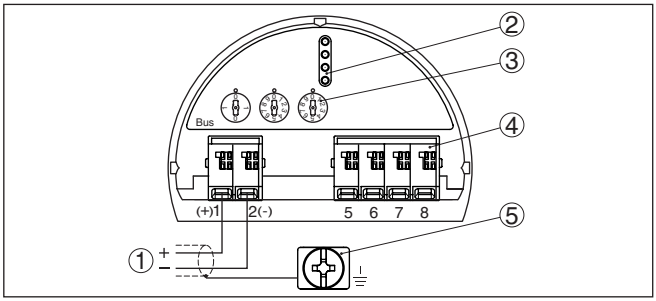



*Fig. 26: Electronics and terminal compartment, single chamber housing*

*1 Voltage supply, signal output*
*2 For display and adjustment module or interface adapter*
*3 Selection switch for bus address*
*4 For external display and adjustment unit*
*5 Ground terminal for connection of the cable screen*

## 5.4 Wiring plan, double chamber housing

The following illustrations apply to the non-Ex as well as to the Ex-ia version.

**Electronics compartment**

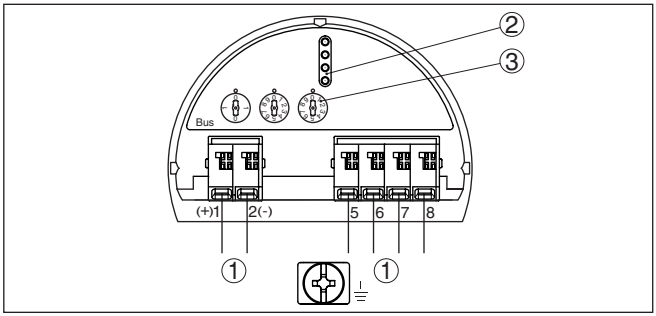



*Fig. 27: Electronics compartment, double chamber housing*

*1 Internal connection to the connection compartment*
*2 Contact pins for the display and adjustment module or interface adapter*
*3 Selection switch for bus address*

**Information:**
The connection of an external display and adjustment unit is not possible with this double chamber housing.

### Terminal compartment

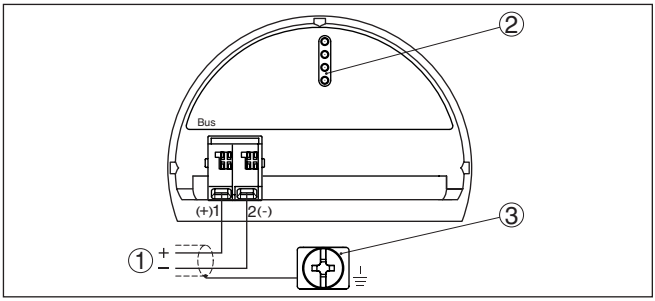



*Fig. 28: Terminal compartment, double chamber housing*

*1 Voltage supply, signal output*
*2 For display and adjustment module or interface adapter*
*3 Ground terminal for connection of the cable screen*

### Connection compartment - Radio module PLICS-MOBILE

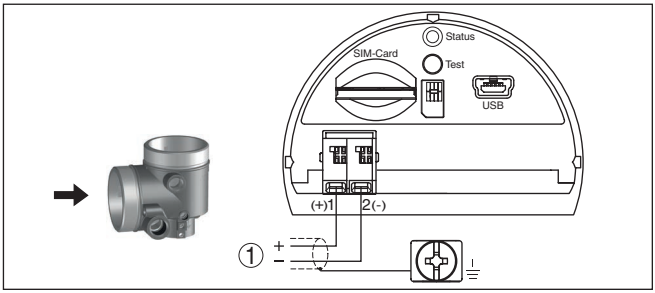



*Fig. 29: Connection compartment radio module PLICSMOBILE*

*1 Voltage supply*

You can find detailed information on connection in the supplementary instructions "*PLICSMOBILE GSM/GPRS radio module*".

## 5.5 Wiring plan, double chamber housing Ex d ia

### Electronics compartment

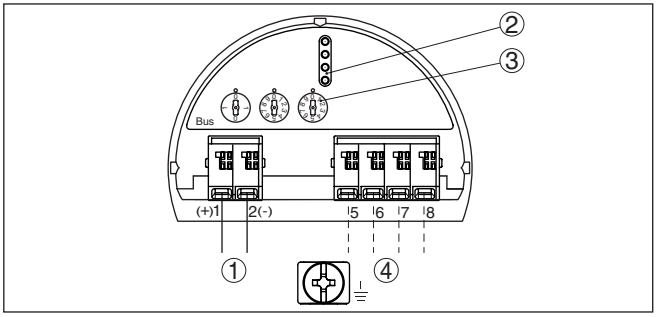



*Fig. 30: Electronics compartment, double chamber housing Ex d ia*

1 *Internal connection to the connection compartment*
2 *Contact pins for the display and adjustment module or interface adapter*
3 *Selection switch for bus address*
4 *Internal connection to the plug connector for external display and adjustment unit (optional)*

### Terminal compartment

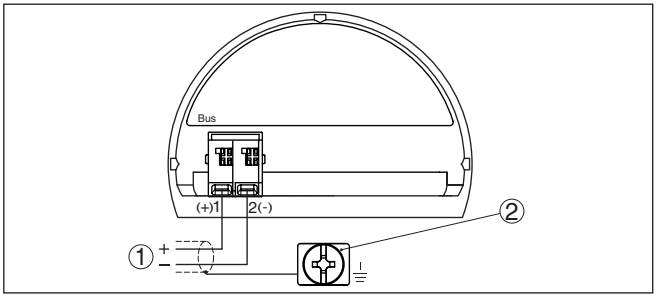



*Fig. 31: Connection compartment, double chamber housing Ex d ia*

1 *Voltage supply, signal output*
2 *Ground terminal for connection of the cable screen*

### Plug M12 x 1 for external display and adjustment unit

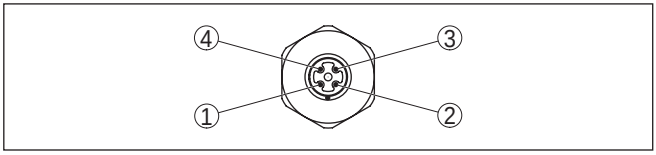



*Fig. 32: Top view of the plug connector*

1 *Pin 1*
2 *Pin 2*
3 *Pin 3*
4 *Pin 4*

| Contact pin | Colour connection cable in the sensor | Terminal, electronics module |
|---|---|---|
| Pin 1 | Brown | 5 |

| Contact pin | Colour connection cable in the sensor | Terminal, electronics module |
|---|---|---|
| Pin 2 | White | 6 |
| Pin 3 | Blue | 7 |
| Pin 4 | Black | 8 |

## 5.6 Double chamber housing with DIS-ADAPT

**Electronics compartment**

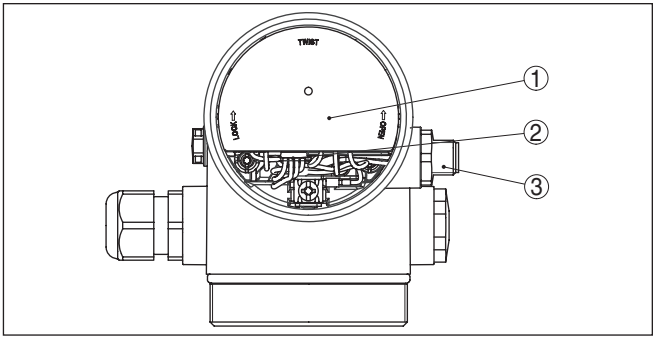



*Fig. 33: View to the electronics compartment*

*1 DIS-ADAPT*
*2 Internal plug connection*
*3 Plug connector M12 x 1*

**Assignment of the plug connector**

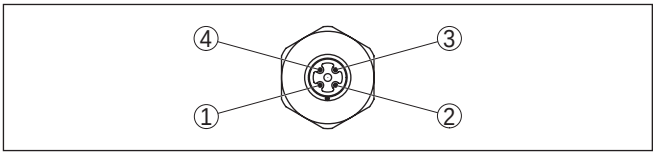



*Fig. 34: Top view of the plug connector*

*1 Pin 1*
*2 Pin 2*
*3 Pin 3*
*4 Pin 4*

| Contact pin | Colour connection cable in the sensor | Terminal, electronics module |
|---|---|---|
| Pin 1 | Brown | 5 |
| Pin 2 | White | 6 |
| Pin 3 | Blue | 7 |
| Pin 4 | Black | 8 |

## 5.7 Wiring plan - version IP 66/IP 68, 1 bar

**Wire assignment, connection cable**

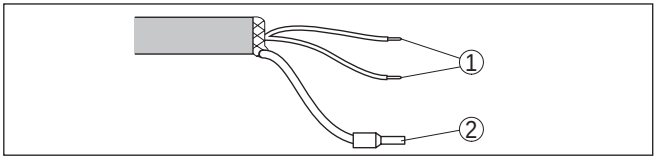



*Fig. 35: Wire assignment in permanently connected connection cable*

*1 brown (+) and blue (-) to power supply or to the processing system*
*2 Shielding*

## 5.8 Set instrument address

**Instrument address**

An address must be assigned to each Profibus PA instrument. The approved addresses are between 0 and 126. Each address must only be assigned once in the Profibus PA network. The sensor is only recognized by the control system if the address is set correctly.

When the instrument is shipped, address 126 is adjusted. This address can be used for function test of the instrument and for connection to a Profibus PA network. Then address must be changed to integrate additional instruments.

The address setting is carried out either via:

- The address selection switch in the electronics compartment of the instrument (address setting via hardware)
- The display and adjustment module (address setting via software)
- PACTware/DTM (address setting via software)

**Hardware addressing**

The hardware addressing is effective if an address <126 is adjusted with the address selection switches on the instrument. Hence the software addressing is no longer effective, the adjusted hardware address is valid.

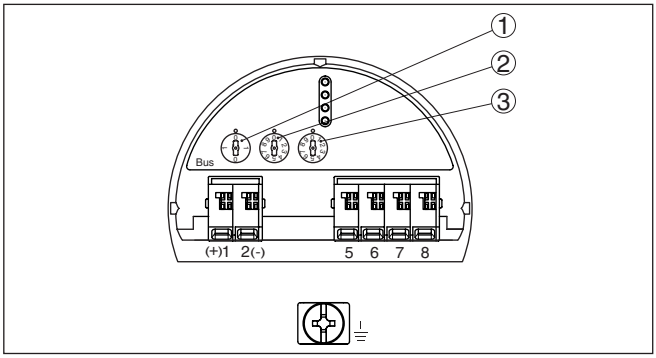



*Fig. 36: Address selection switch*

*1 Addresses <100 (selection 0), addresses >100 (selection 1)*
*2 Decade of the address (selection 0 to 9)*
*3 Unit position of the address (selection 0 to 9)*

**Software addressing**

The software addressing is only effective if address 126 or higher is adjusted on the instrument with the address selection switches.

The addressing procedure is described in the operating instructions manual "*Display and adjustment module*.

## 5.9 Switch-on phase

After VEGAPULS 68 is connected to the bus system, the instrument carries out a self-test for approx. 30 seconds. The following steps are carried out:

- Internal check of the electronics
- Indication of the instrument type, hardware and software version, measurement loop name on the display or PC
- Indication of the status message "*F 105 Determine measured value*" on the display or PC
- Status byte goes briefly to fault value

As soon as a plausible measured value is found, it is outputted to the signal cable. The value corresponds to the actual level as well as the settings already carried out, e.g. factory settings.

# 6 Set up with the display and adjustment module

## 6.1 Insert display and adjustment module

The display and adjustment module can be inserted into the sensor and removed again at any time. You can choose any one of four different positions - each displaced by 90°. It is not necessary to interrupt the power supply.

Proceed as follows:

1. Unscrew the housing cover
2. Place the display and adjustment module in the requested position onto the electronics and turn to the right until it snaps in
3. Screw housing cover with inspection window tightly back on

Removal is carried out in reverse order.

The display and adjustment module is powered by the sensor, an additional connection is not necessary.

*Fig. 37: Installing the display and adjustment module in the electronics compartment of the single chamber housing*

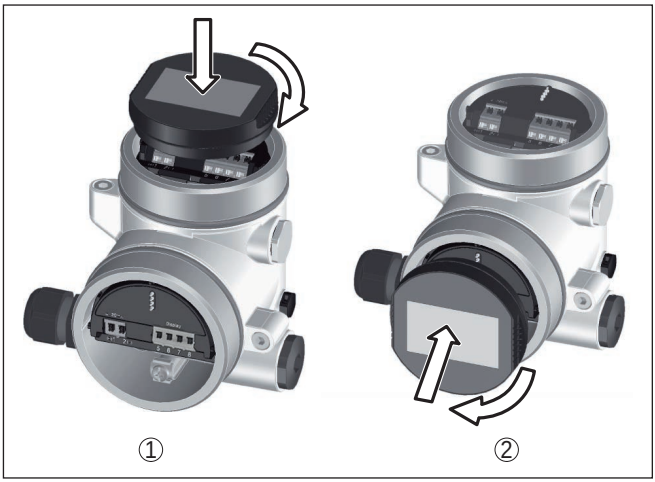



*Fig. 38: Insertion of the display and adjustment module into the double chamber housing*

*1 In the electronics compartment*
*2 In the connection compartment (with Ex-d-ia version not possible)*

**Note:**
If you intend to retrofit the instrument with a display and adjustment module for continuous measured value indication, a higher cover with an inspection glass is required.

## 6.2 Adjustment system

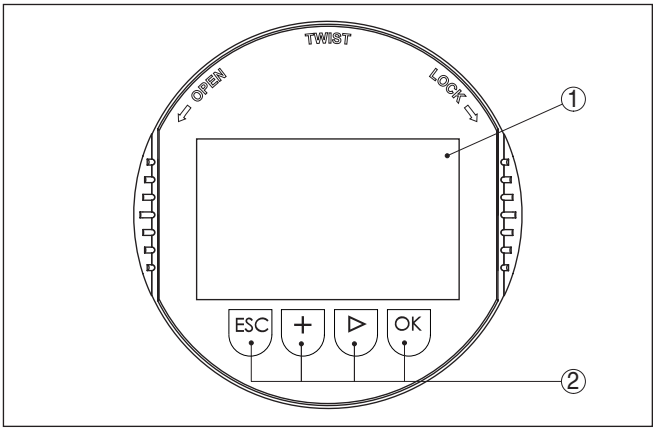



*Fig. 39: Display and adjustment elements*

*1 LC display*
*2 Adjustment keys*

**Key functions**

- ***[OK]*** key:
  – Move to the menu overview

- Confirm selected menu
- Edit parameter
- Save value

- ***[-]*** key:
  - Presentation, change measured value
  - Select list entry
  - Select editing position
- ***[+]*** key:
  - Change value of the parameter
- ***[ESC]*** key:
  - Interrupt input
  - Jump to next higher menu

**Adjustment system**

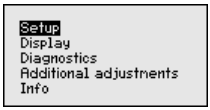
The device is adjusted via the four keys of the display and adjustment module. The LC display indicates the individual menu items. The functions of the individual keys are shown in the above illustration. Approx. 60 minutes after the last pressing of a key, an automatic reset to measured value indication is triggered. Any values not confirmed with ***[OK]*** will not be saved.

## 6.3 Parameter adjustment

The instrument is adapted to the application conditions via the parameter adjustment. The parameter adjustment is carried out with an adjustment menu.

**Main menu**

The main menu is divided into five sections with the following functions:




**Setup:** Settings, for example, to measurement loop name, medium, application, vessel, adjustment, AI FB 1 Channel - scaling - damping

**Display:** Language setting, settings for the measured value indication as well as lighting

**Diagnosis:** Information, for example on the instrument status, pointer, reliability, AI FB 1 simulation, echo curve

**Further settings:** Instrument units, false signal suppression, linearization, sensor address, PIN, date/time, reset, copy sensor data

**Info:** Instrument name, hardware and software version, date of manufacture, instrument features

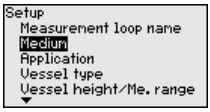
In the main menu point "*Setup*", the individual submenu points should be selected one after the other and provided with the correct parameters to ensure optimum adjustment of the measurement. The procedure is described in the following.

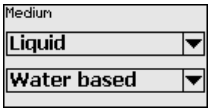
## Setup

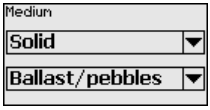
### Setup - Medium

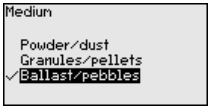
Each medium has different reflection properties. With liquids, further interfering factors are fluctuation product surface and foam generation. With bulk solids, these are dust generation, material cone and additional echoes from the vessel wall.

To adapt the sensor to these different measuring conditions, the selection "*Liquid*" or "*Bulk solid*" should be made in this menu item.





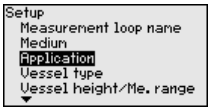

Through this selection, the sensor is adapted perfectly to the product and measurement reliability, particularly in products with poor reflective properties, is considerably increased.

Enter the requested parameters via the appropriate keys, save your settings with ***[OK]*** and jump to the next menu item with the ***[ESC]*** and the ***[->]*** key.

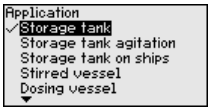
### Setup - Application

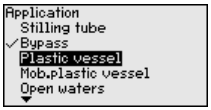
In addition to the medium, also the application, i.e. the measuring site, can influence the measurement.

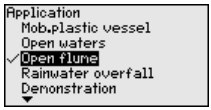
With this menu item, the sensor can be adapted to the applications. The adjustment possibilities depend on the selection "*Liquid*" or "*Bulk solid*" under "*Medium*".



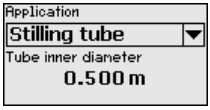

The following options are available when "*Liquid*" is selected:

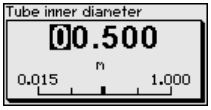



The selection "*Standpipe*" opens a new window in which the inner diameter of the applied standpipe is entered.




The following features form the basis of the applications:

**Storage tank:**

- Setup: large-volumed, upright cylindrical, spherical
- Product speed: slow filling and emptying
- Process/measurement conditions:

  - Condensation
  - Smooth product surface
  - High requirements to the measurement accuracy
- Properties, sensor:
  - Slight sensitivity against sporadic false echoes
  - Stable and reliable measured values by averaging
  - High accuracy
  - Short reaction time of the sensor not required

**Storage tanke with product circulation:**

- Setup: large-volumed, upright cylindrical, spherical
- Product speed: slow filling and emptying
- Installations: small laterally mounted or large top mounted stirrer
- Process/measurement conditions:
  - Relatively smooth product surface
  - High requirements to the measurement accuracy
  - Condensation
  - Slight foam generation
  - Overfilling possible
- Properties, sensor:
  - Slight sensitivity against sporadic false echoes
  - Stable and reliable measured values by averaging
  - High accuracy because not adjusted for max. speed
  - False signal suppression recommended

**Storage tank on ships (Cargo Tank):**

- Product speed: slow filling and emptying
- Vessel:
  - Installations in the bottom section (bracers, heating spirals)
  - High sockets 200 … 500 mm, also with large diameters
- Process/measurement conditions:
  - Condensation, buildup by movement
  - Max. requirement on measurement accuracy from 95 %
- Properties, sensor:
  - Slight sensitivity against sporadic false echoes
  - Stable and reliable measured values by averaging
  - High accuracy
  - False signal suppression required

**Stirrer vessel (reactor):**

- Setup: all vessel sizes possible
- Product speed:
  - Fast to slow filling possible
  - Vessel is very often filled and emptied
- Vessel:
  - Socket available
  - Large agitator blades of metal
  - Vortex breakers, heating spirals
- Process/measurement conditions:
  - Condensation, buildup by movement
  - Strong spout generation
  - Very agitated surface, foam generation
- Properties, sensor:

- Higher measurement speed through lower averaging
- Sporadic false echoes are suppressed

**Dosing vessel:**

- Setup: all vessel sizes possible
- Product speed:
  - Fast filling and emptying
  - Vessel is very often filled and emptied
- Vessel: narrow installation situation
- Process/measurement conditions:
  - Condensation, buildup on the antenna
  - Foam generation
- Properties, sensor:
  - Measurement speed optimized by virtually no averaging
  - Sporadic false echoes are suppressed
  - False signal suppression recommended

**Standpipe:**

- Product speed: very fast filling and emptying
- Vessel:
  - Vent hole
  - Joins like flanges, weld joints
  - Shifting of the running time in the tube
- Process/measurement conditions:
  - Condensation
  - Buildup
- Properties, sensor:
  - Measurement speed optimized through little averaging
  - Entering the tube inside diameter takes the running time shift into consideration
  - Echo detection sensitivity reduced

**Bypass:**

- Product speed:
  - Fast up to slow filling with short up to long bypass tube possible
  - Often the level is hold via a control facility
- Vessel:
  - Lateral outlets and inlets
  - Joins like flanges, weld joints
  - Shifting of the running time in the tube
- Process/measurement conditions:
  - Condensation
  - Buildup
  - Separation of oil and water possible
  - Overfilling into the antenna possible
- Properties, sensor:
  - Measurement speed optimized through little averaging
  - Entering the tube inside diameter takes the running time shift into consideration
  - Echo detection sensitivity reduced
  - False signal suppression recommended

**Plastic tank:**

- Vessel:
  - Measurement fix mounted or integrated
  - Measurement depending on the application through the vessel top
  - With empty vessel, the measurement can be carried out through the bottom
- Process/measurement conditions:
  - Condensation on the plastic ceiling
  - In outside facilities water and snow on the vessel top possible
- Properties, sensor:
  - False signals outside the vessel are not taken into consideration
  - False signal suppression recommended

**Transportable plastic tank:**

- Vessel:
  - Material and thickness different
  - Measurement through the vessel top
- Process/measurement conditions:
  - Measured value jump with vessel change
- Properties, sensor:
  - Quick adaptation to changing reflection conditions through vessel change
  - False signal suppression required

**Open water (gauge measurement):**

- Gauge rate of change: slow gauge change
- Process/measurement conditions:
  - Distance sensor to water surface to big
  - Extreme damping of output signal due to wave generation
  - Ice and condensation on the antenna possible
  - Spiders and insect nestle in the antennas
  - Floating material and animals sporadically on the water surface
- Properties, sensor:
  - Stable and reliable measured values by high averaging
  - Insensitive in the close range

**Open flume (flow measurement):**

- Gauge rate of change: slow gauge change
- Process/measurement conditions:
  - Ice and condensation on the antenna possible
  - Spiders and insect nestle in the antennas
  - Smooth water surface
  - Exact measurement result required
  - Distance to the water surface normally relatively high
- Properties, sensor:
  - Stable and reliable measured values by high averaging
  - Insensitive in the close range

**Rain water overfall (weir):**

- Gauge rate of change: slow gauge change
- Process/measurement conditions:
  - Ice and condensation on the antenna possible

- Spiders and insect nestle in the antennas
- Turbulent water surface
- Sensor flooding possible

- Properties, sensor:
  - Stable and reliable measured values by high averaging
  - Insensitive in the close range

**Demonstration:**

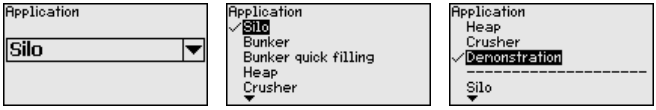
- Adjustment for all applications which are not typically level measurement
  - Instrument demonstration
  - Object recognition/monitoring (additional settings required)
- Properties, sensor:
  - Sensor accepts all measured value changes within the measuring range immediately
  - High sensitivity against interferences, because virtually no averaging

**Caution:**

If a separation of liquids with different dielectric constant occurs in the vessel, for example through condensation, the radar sensor can detect under certain circumstances only the medium with the higher dielectric constant. Keep in mind that layer interfaces can cause faulty measurements.

If you want to measure the total height of both liquids reliably, please contact our service department or use an instrument specially designed for interface measurement.

The following options are available when "*Bulk solid*" is selected:




The following features form the basis of the applications:

**Silo (slim and high):**

- Vessel of metal: weld joints
- Process/measurement conditions:
  - Filling too close to the sensor
  - System noise with completely empty silo increased
- Properties, sensor:
  - Stable measured values through higher averaging
  - False signal suppression recommended with setup, required for automatic false signal suppression
  - Automatic false signal suppression with partly filled vessel

**Bunker (large-volumed):**

- Vessel of concrete or metal:
  - Structured vessel walls
  - Installations present
- Process/measurement conditions:
  - Large distance to the medium
  - Large angles of repose

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- Properties, sensor:
  - Mean averaging
  - High measured value jumps are accepted

**Bunker with fast filling:**
- Vessel of concrete or metal, also multiple chamber silo:
  - Structured vessel walls
  - Installations present
- Process/measurement conditions:
  - Measured value jumps, e.g. by truck loading
  - Large distance to the medium
  - Large angles of repose
- Properties, sensor:
  - Lower averaging
  - Very high measured value jumps are accepted

**Heap:**
- Sensor mounting on movable conveyor belts
- Detection of the heap profile
- Height detection during filling
- Process/measurement conditions:
  - Measured value jumps, e.g. by the profile of the heap or traverses
  - Large angles of repose
  - Measurement near the filling stream
- Properties, sensor:
  - Mean averaging
  - High measured value jumps are accepted

**Crusher:**
- Vessel: installations, wear and protective facilities available
- Process/measurement conditions:
  - Measured value jumps, e.g. by truck loading
  - Fast reaction time
  - Large distance to the medium
- Properties, sensor:
  - Little averaging
  - Max. reaction speed, very high measured value jumps are accepted

**Demonstration:**
- Adjustment for all applications which are not typically level measurement
  - Instrument demonstration
  - Object recognition/monitoring (additional settings required)
- Properties, sensor:
  - Sensor accepts all measured value changes within the measuring range immediately
  - High sensitivity against interferences, because virtually no averaging

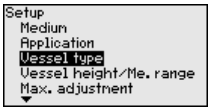
Through this selection, the sensor is adapted optimally to the application or the location and measurement reliability under the various basic conditions is increased considerably.

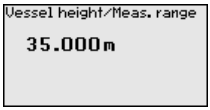
Enter the requested parameters via the appropriate keys, save your settings with ***[OK]*** and jump to the next menu item with the ***[ESC]*** and the ***[->]*** key.

**Setup - Vessel height, measuring range**

With this selection, the operating range of the sensor is adapted to the vessel height and the reliability with different frame conditions is increased considerably.

Independent from this, the min. adjustment must be carried out.

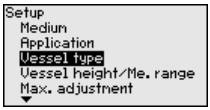


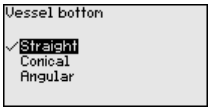




Enter the requested parameters via the appropriate keys, save your settings with ***[OK]*** and jump to the next menu item with the ***[ESC]*** and the ***[->]*** key.

**Setup - Vessel form**

Also the vessel form can influence the measurement apart from the medium and the application. To adapt the sensor to these measurement conditions, this menu item offers you different options for vessel bottom and ceiling in case of certain applications.



Enter the requested parameters via the appropriate keys, save your settings with ***[OK]*** and jump to the next menu item with the ***[ESC]*** and the ***[->]*** key.

**Setup - Adjustment**

Since the radar sensor is a distance measuring instrument, the distance from the sensor to the product surface is measured. For indication of the real level, an allocation of the measured distance to the percentage height must be carried out.

To perform the adjustment, enter the distance with full and empty vessel, see the following example:

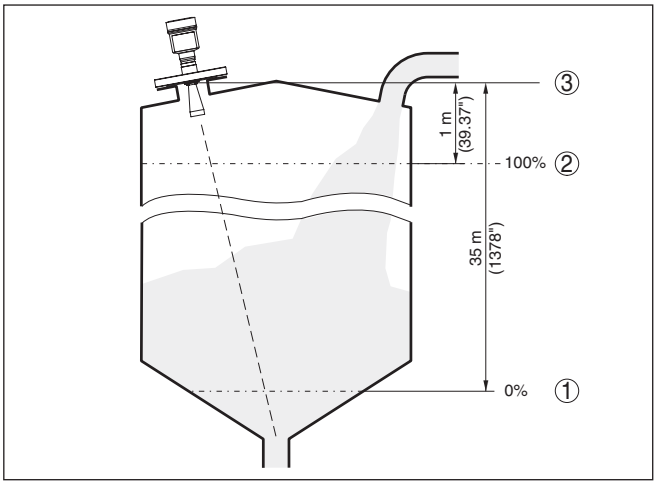



*Fig. 40: Parameter adjustment example min./max. adjustment*

*1 Min. level = max. meas. distance*
*2 Max. level = min. meas. distance*

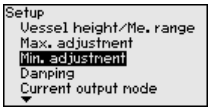
If these values are not known, an adjustment with the distances of for example 10 % and 90 % is possible. Starting point for these distance specifications is always the seal surface of the thread or flange. You can find specifications of the reference plane in chapter "*Technical data*". By means of these settings, the real level will be calculated.

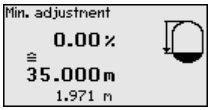
The real product level during this adjustment is not important, because the min./max. adjustment is always carried out without changing the product level. These settings can be made ahead of time without the instrument having to be installed.

**Setup - Min. adjustment**

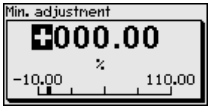
Proceed as follows:

1. Select the menu item "*Setup*" with ***[->]*** and confirm with ***[OK]***. Now select with ***[->]*** the menu item "*Min. adjustment*" and confirm with ***[OK]***.

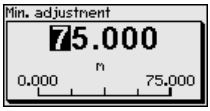



2. Edit the percentage value with ***[OK]*** and set the cursor to the requested position with ***[->]***.




3. Set the requested percentage value with ***[+]*** and save with ***[OK]***. The cursor jumps now to the distance value.

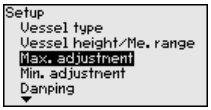


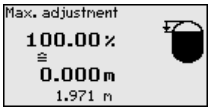

4. Enter the suitable distance value in m for the empty vessel (e.g. distance from the sensor to the vessel bottom) corresponding to the percentage value.
5. Save settings with ***[OK]*** and move with ***[ESC]*** and ***[->]*** to the max. adjustment.

**Setup - Max. adjustment**

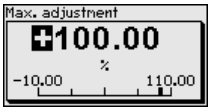
Proceed as follows:

1. Select with ***[->]*** the menu item "Max. adjustment" and confirm with ***[OK]***.

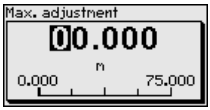



2. Prepare the percentage value for editing with ***[OK]*** and set the cursor to the requested position with ***[->]***.



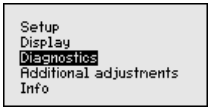

3. Set the requested percentage value with ***[+]*** and save with ***[OK]***. The cursor jumps now to the distance value.

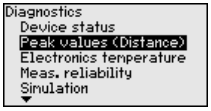


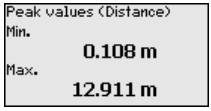

4. Enter the appropriate distance value in m (corresponding to the percentage value) for the full vessel. Keep in mind that the max. level must lie below the min. distance to the antenna edge.
5. Save settings with ***[OK]***

**Diagnosis - Peak value**

The respective min. and max. measured value is saved in the sensor. The values are displayed in the menu item "*Peak values*".

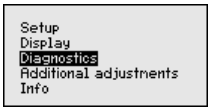


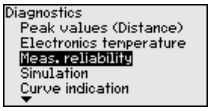



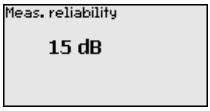




**Diagnosis - Measurement reliability**

When non-contact level sensors are used, the measurement can be influenced by the respective process conditions. In this menu item, the measurement reliability of the level echo is displayed as dB value. The measurement reliability equals signal strength minus noise. The higher the value, the more reliable the measurement. With a functioning measurement, the values are > 10 dB.

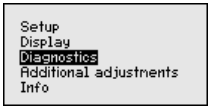


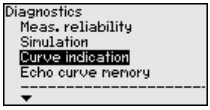



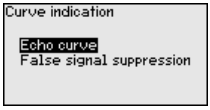




**Diagnoses - Curve indication**

The "*Echo curve*" shows the signal strength of the echoes over the measuring range in dB. The signal strength enables an evaluation of the quality of the measurement.

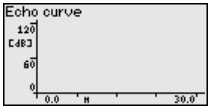


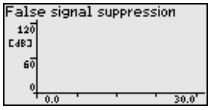




The "*False signal suppression*" displays the saved false echoes (see menu "*Additional settings*") of the empty vessel with signal strength in "dB" over the measuring range.

A comparison of echo curve and false signal suppression allows a more detailed statement of the reliability.



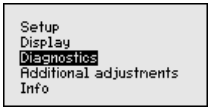

The selected curve is permanently updated. A submenu with zoom functions is opened with the ***[OK]*** key:

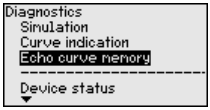
- "X-Zoom": Zoom function for the meas. distance
- "Y-Zoom": 1, 2, 5 and 10x signal magnification in "*dB*"
- "Unzoom": Reset the presentation to the nominal measuring range with single magnification

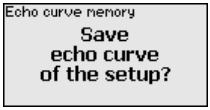
**Diagnostics - Echo curve memory**

With the function "*Echo curve memory*" the echo curve can be saved at the time of setup. This is generally recommended; for using the Asset Management functions it is absolutely necessary. If possible, the curve should be saved with a low level in the vessel.

With the adjustment software PACTware and the PC, the high resolution echo curve can be displayed and used to recognize signal changes over the operating time. In addition, the echo curve of the setup can be also displayed in the echo curve window and compared with the actual echo curve.




**Additional adjustments - False signal suppression**

The following circumstances cause interfering reflections and can influence the measurement:

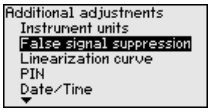
- High sockets
- Vessel installations such as struts
- Agitators
- Buildup or welded joints on vessel walls

**Note:**
A false signal suppression detects, marks and saves these false signals so that they are no longer taken into account for level measurement.

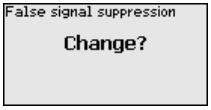
This should be done with the low level so that all potential interfering reflections can be detected.

Proceed as follows:

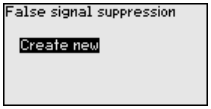
1. Select the menu item "*Additional settins*" with ***[->]*** and confirm with ***[OK]***. With ***[->]*** you have to select the menu item "*False signal suppression*" and confirm with ***[OK]***.



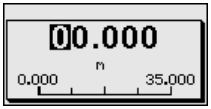

2. Confirm again with ***[OK]***.




3. Confirm again with ***[OK]***.



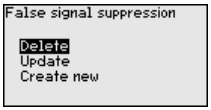

4. Confirm again with ***[OK]*** and enter the actual distance from the sensor to the product surface.




5. All interfering signals in this section are detected by the sensor and stored after confirming with ***[OK]***.

**Note:**
Check the distance to the product surface, because if an incorrect (too large) value is entered, the existing level will be saved as a false echo. The filling level would then no longer be detectable in this area.

If a false signal suppression has already been created in the sensor, the following menu window appears when selecting "*False signal suppression*":



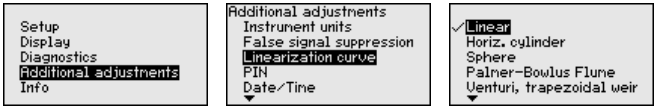

The menu item "*Delete*" is used to completely delete an already created false signal suppression. This is useful if the saved false signal suppression no longer matches the metrological conditions in the vessel.

The menu item "*Extend*" is used to extend an already created false signal suppression. This is useful if a false signal suppression was carried out with a too high level and not all false signals could be detected. When selecting "*Extend*", the distance to the product surface of the created false signal suppression is displayed. This value can now be changed and the false signal suppression can be extended to this range.

**Additional adjustments - Linearization curve**

A linearization is necessary for all vessels in which the vessel volume does not increase linearly with the level - e.g. a horizontal cylindrical or spherical tank - and the indication or output of the volume is required. Corresponding linearization curves are preprogrammed for these vessels. They represent the correlation between the level percentage and vessel volume.

By activating the appropriate curve, the volume percentage of the vessel is displayed correctly. If the volume should not be displayed in percent but e.g. in l or kg, a scaling can be also set in the menu item "*Display*".




Enter the requested parameters via the appropriate keys, save your settings and jump to the next menu item with the ***[ESC]*** and ***[->]*** key.

**Caution:**

Note the following if the instrument with corresponding approval is used as part of an overfill protection system according to WHG:

If a linearization curve is selected, the measuring signal is no longer necessarily linear to the filling height. This must be considered by the user especially when adjusting the switching point on the limit signal transmitter.

**Additional adjustments - Reset**

When a reset is carried out, all settings (with only a few exceptions) are reset. The exceptions are: PIN, language, lighting, SIL and HART mode.

The following reset functions are available:

- **Delivery status:** Restoring the parameter settings at the time of shipment from the factory incl. the order-specific settings. A created false signal suppression, user-programmable linearization curve, the measured value memory, echo curve memory as well as event memory will be deleted.
- **Basic settings:** Resetting of the parameter settings incl. special parameters to the default values of the respective instrument. Any created false signal suppression, user programmable linearization curve, measured value memory as well as event memory will be deleted.

- **Setup:** Resetting of the parameter settings to the default values of the respective instrument . Order-related settings remain but are not taken over into the current parameters. User-generated false signal suppression, user-programmed linearization curve, measured value memory, echo curve memory as well as event memory remain untouched. The linearization is set to linear.
- **False signal suppression:** Deleting a previously created false signal suppression. The false signal suppression created in the factory remains active.
- **Peak values measured value:** Resetting of the measured min. and max. distances to the actual measured value.

Select the requested reset function ***[->]*** and confirm with ***[OK]***.

The following table shows the default values of VEGAPULS 68:

| Menu | Menu item | Default value |
|---|---|---|
| Setup | Measurement loop name | Sensor |
| | Medium | Liquid/Water<br>Bulk solids/Crushed stones, gravel |
| | Application | Storage tank<br>Silo |
| | Vessel form | Vessel bottom, dished boiler end<br>Vessel top, dished boiler end |
| | Vesell height/ Measuring range | Recommended measuring range, see "*Technical data*" in the supplement |
| | Min. adjustment | Recommended measuring range, see "*Technical data*" in the supplement |
| | Max. adjustment | 0,000 m(d) |
| | AI FB1 Channnel | PV (lin. perc.) |
| | AI FB1 scaling unit | Height<br>% |
| | AI FB1 scaling | 0.00 lin %, 0.00 %<br>100.00 lin %, 100.00 % |
| | AI FB1 damping | 0 s |
| | Block adjustment | Released |
| Display | Language | Like order |
| | Displayed value | SV 1 |
| | Backlight | Switched off |

| Menu | Menu item | Default value |
|---|---|---|
| Additional adjustments | Distance unit | m |
| | Temperature unit | °C |
| | Unit SV2 | m |
| | Probe length | Length of the standpipe Ex factory |
| | Linearisation curve | Linear |
| | Sensor address | 126 |

## 6.4 Saving the parameter adjustment data

We recommended noting the adjusted data, e.g. in this operating instructions manual, and archiving them afterwards. They are thus available for multiple use or service purposes.

If the instrument is equipped with a display and adjustment module, the data in the sensor can be saved in the display and adjustment module. The procedure is described in the operating instructions manual "*Display and adjustment module*" in the menu item "*Copy sensor data*". The data remain there permanently even if the sensor power supply fails.

The following data or settings for adjustment of the display and adjustment module are saved:

- All data of the menu "*Setup*" and "*Display*"
- In the menu "*Additional adjustments*" the items "*Sensor-specific units, temperature unit and linearization*"
- The values of the user programmable linearization curve

The function can also be used to transfer settings from one instrument to another instrument of the same type. If it is necessary to exchange a sensor, the display and adjustment module is inserted into the replacement instrument and the data are likewise written into the sensor via the menu item "*Copy sensor data*".

# 7 Setup with PACTware

## 7.1 Connect the PC

**Via the interface adapter directly on the sensor**

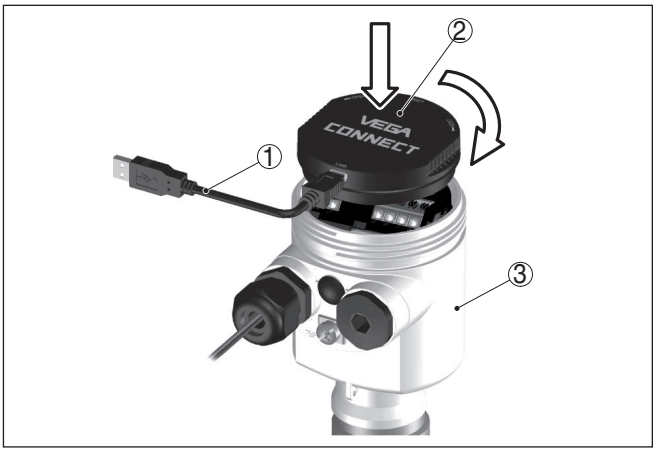



*Fig. 41: Connection of the PC directly to the sensor via the interface adapter*

*1 USB cable to the PC*
*2 Interface adapter VEGACONNECT*
*3 Sensor*

## 7.2 Parameter adjustment

**Prerequisites**

For parameter adjustment of the sensor via a Windows PC, the configuration software PACTware and a suitable instrument driver (DTM) according to FDT standard are required. The up-to-date PACTware version as well as all available DTMs are compiled in a DTM Collection. The DTMs can also be integrated into other frame applications according to FDT standard.

**Note:**
To ensure that all instrument functions are supported, you should always use the latest DTM Collection. Furthermore, not all described functions are included in older firmware versions. You can download the latest instrument software from our homepage. A description of the update procedure is also available in the Internet.

Further setup steps are described in the operating instructions manual "*DTM Collection/PACTware*" attached to each DTM Collection and which can also be downloaded from the Internet. Detailed descriptions are available in the online help of PACTware and the DTMs.

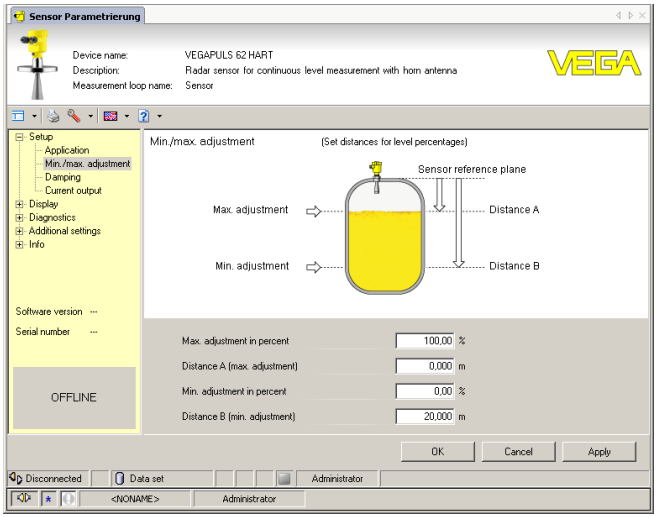



*Fig. 42: Example of a DTM view*

**Standard/Full version**

All device DTMs are available as a free-of-charge standard version and as a full version that must be purchased. In the standard version, all functions for complete setup are already included. An assistant for simple project configuration simplifies the adjustment considerably. Saving/printing the project as well as import/export functions are also part of the standard version.

In the full version there is also an extended print function for complete project documentation as well as a save function for measured value and echo curves. In addition, there is a tank calculation program as well as a multiviewer for display and analysis of the saved measured value and echo curves.

The standard version is available as a download under www.vega.com/downloads and "*Software*". The full version is available on CD from the agency serving you.

## 7.3 Saving the parameter adjustment data

We recommend documenting or saving the parameter adjustment data via PACTware. That way the data are available for multiple use or service purposes.

# 8 Set up with other systems

## 8.1 DD adjustment programs

Device descriptions as Enhanced Device Description (EDD) are available for DD adjustment programs such as, for example, AMS™ and PDM.

The files can be downloaded at www.vega.com/downloads under "*Software*".

# 9 Diagnosis, asset management and service

## 9.1 Maintenance

If the device is used correctly, no maintenance is required in normal operation.

In some applications, buildup on the antenna system can influence the measuring result. Depending on the sensor and application, make arrangements to avoid strong pollution of the antenna system. If necessary, clean the antenna system in certain intervals.

## 9.2 Measured value and event memory

The instrument has several memories which are available for diagnosis purposes. The data remain even with voltage interruption.

**Measured value memory**

Up to 60,000 measured values can be stored in the sensor in a ring memory. Each entry contains date/time as well as the respective measured value. Storable values are for example:

- Distance
- Filling height
- Percentage value
- Lin. percent
- Scaled
- Current value
- Meas. reliability
- Electronics temperature

When the instrument is shipped, the measured value memory is active and stores distance, measurement certainty and electronics temperature every 3 minutes.

The requested values and recording conditions are set via a PC with PACTware/DTM or the control system with EDD. Data are thus read out and also reset.

**Event memory**

Up to 500 events are automatically stored with a time stamp in the sensor (non-deletable). Each entry contains date/time, event type, event description and value. Event types are for example:

- Modification of a parameter
- Switch-on and switch-off times
- Status messages (according to NE 107)
- Error messages (according to NE 107)

The data are read out via a PC with PACTware/DTM or the control system with EDD.

**Echo curve memory**

The echo curves are stored with date and time and the corresponding echo data. The memory is divided into two sections:

**Echo curve of the setup:** This is used as reference echo curve for the measurement conditions during setup. Changes in the measurement conditions during operation or buildup on the sensor can thus be recognized. The echo curve of the setup is stored via:

- PC with PACTware/DTM
- Control system with EDD
- Display and adjustment module

**Further echo curves:** Up to 10 echo curves can be stored in a ring buffer in this memory section. Further echo curves are stored via:

- PC with PACTware/DTM
- Control system with EDD

## 9.3 Asset Management function

The instrument features self-monitoring and diagnostics according to NE 107 and VDI/VDE 2650. In addition to the status messages in the following tables there are more detailed error messages available under the menu item "*Diagnostics*" via the display and adjustment module, PACTware/DTM and EDD.

**Status messages**

The status messages are divided into the following categories:

- Failure
- Function check
- Out of specification
- Maintenance requirement

and explained by pictographs:

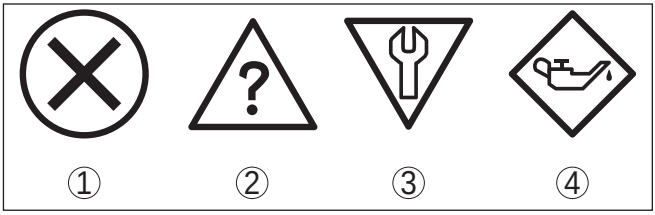



*Fig. 43: Pictographs of the status messages*

*1 Failure - red*
*2 Out of specification - yellow*
*3 Function check - orange*
*4 Maintenance - blue*

**Failure:** Due to a malfunction in the instrument, a failure message is outputted.

This status message is always active. It cannot be deactivated by the user.

**Function check:** The instrument is in operation, the measured value is temporarily invalid (for example during simulation).

This status message is inactive by default. It can be activated by the user via PACTware/DTM or EDD.

**Out of specification:** The measured value is unstable because the instrument specification is exceeded (e.g. electronics temperature).

This status message is inactive by default. It can be activated by the user via PACTware/DTM or EDD.

**Maintenance:** Due to external influences, the instrument function is limited. The measurement is affected, but the measured value is still valid. Plan in maintenance for the instrument because a failure is expected in the near future (e.g. due to buildup).

This status message is inactive by default. It can be activated by the user via PACTware/DTM or EDD.

**Failure (failure)**

The following table shows the codes and text messages of the status message "*Failure*" and provides information on causes as well as corrective measures.

| Code<br>Text message | Cause | Rectification | PA DevSpec<br>Diagnosis |
|---|---|---|---|
| F013<br>no measured value available | – Sensor does not detect an echo during operation<br>– Antenna system contaminated or defective | – Check or correct installation and/or parameter adjustment<br>– Clean or exchange process component or antenna | Bit 0 |
| F017<br>Adjustment span too small | – Adjustment not within specification | – Change adjustment according to the limit values (difference between min. and max. ≥ 10 mm) | Bit 1 |
| F025<br>Error in the linearization table | – Index markers are not continuously rising, for example illogical value pairs | – Check linearization table<br>– Delete table/Create new | Bit 2 |
| F036<br>No operable software | – Failed or interrupted software update | – Repeat software update<br>– Check electronics version<br>– Exchanging the electronics<br>– Send instrument for repair | Bit 3 |
| F040<br>Error in the electronics | – Hardware defect | – Exchanging the electronics<br>– Send instrument for repair | Bit 4 |
| F080 | – General software error | – Disconnect operating voltage briefly | Bit 5 |
| F105<br>Determine measured value | – The instrument is still in the start phase, the measured value could not yet be determined | – Wait for the end of the switch-on phase<br>– Duration depending on the version and parameter adjustment up to approximately 3 min. | Bit 6 |

| Code<br>Text message | Cause | Rectification | PA DevSpec<br>Diagnosis |
|---|---|---|---|
| F113<br>Communication error | – Error in the internal instrument communication | – Disconnect operating voltage briefly<br>– Send instrument for repair | Bit 7 |
| F125<br>Impermissible electronics temperature | – Temperature of the electronics in the non-specified section | – Check ambient temperature<br>– Isolate electronics<br>– Use instrument with higher temperature range | Bit 8 |
| F260<br>Error in the calibration | – Error in the calibration carried out in the factory<br>– Error in the EEPROM | – Exchanging the electronics<br>– Send instrument for repair | Bit 9 |
| F261<br>Error in the configuration | – Error during setup<br>– False signal suppression faulty<br>– Error when carrying out a reset | – Repeat setup<br>– Repeat reset | Bit 10 |
| F264<br>Installation/Setup error | – Adjustment not within the vessel height/ measuring range<br>– Max. measuring range of the instrument not sufficient | – Check or correct installation and/or parameter adjustment<br>– Use an instrument with bigger measuring range | Bit 11 |
| F265<br>Measurement function disturbed | – Sensor no longer carries out a measurement<br>– Operating voltage too low | – Check operating voltage<br>– Carry out a reset<br>– Disconnect operating voltage briefly | Bit 12 |

**Function check**

The following table shows the error codes and text messages in the status message "*Function check*" and provides information on causes as well as corrective measures.

| Code<br>Text message | Cause | Rectification |
|---|---|---|
| C700<br>Simulation active | – A simulation is active | – Finish simulation<br>– Wait for the automatic end after 60 mins. |

**Out of specification**

The following table shows the error codes and text messages in the status message "*Out of specification*" and provides information on causes as well as corrective measures.

| Code<br>Text message | Cause | Rectification |
|---|---|---|
| S600<br>Impermissible electronics temperature | – Temperature of the electronics in the non-specified section | – Check ambient temperature<br>– Isolate electronics<br>– Use instrument with higher temperature range |
| S601<br>Overfilling | – Danger of vessel overfilling | – Make sure that there is no further filling<br>– Check level in the vessel |
| S603<br>Impermissible operating voltage | – Operating voltage below specified range | – Check electrical connection<br>– if necessary, increase operating voltage |

**Maintenance**

The following table shows the error codes and text messages in the status message "*Maintenance*" and provides information on causes as well as corrective measures.

| Code<br>Text message | Cause | Rectification |
|---|---|---|
| M500<br>Error with the reset delivery status | – With the reset to delivery status, the data could not be restored | – Repeat reset<br>– Load XML file with sensor data into the sensor |
| M501<br>Error in the non-active linearization table | – Hardware error EEPROM | – Exchanging the electronics<br>– Send instrument for repair |
| M502<br>Error in the diagnosis memory | – Hardware error EEPROM | – Exchanging the electronics<br>– Send instrument for repair |
| M503<br>Reliability too low | – The echot/noise ratio is the small for a reliable measurement | – Check installation and process conditions<br>– Clean the antenna<br>– Change polarisation direction<br>– Use instrument with higher sensitivity |
| M504<br>Error on an device interface | – Hardware defect | – Check connections<br>– Exchanging the electronics<br>– Send instrument for repair |

| Code<br>Text message | Cause | Rectification |
|---|---|---|
| M505<br>No echo available | – Level echo can no longer be detected | – Clean the antenna<br>– Use a more suitable antenna/sensor<br>– Remove possible false echoes<br>– Optimize sensor position and orientation |

## 9.4 Rectify faults

**Reaction when malfunctions occur**

The operator of the system is responsible for taking suitable measures to rectify faults.

**Procedure for fault rectification**

The first measures are:

- Evaluation of fault messages, for example via the display and adjustment module
- Checking the output signal
- Treatment of measurement errors

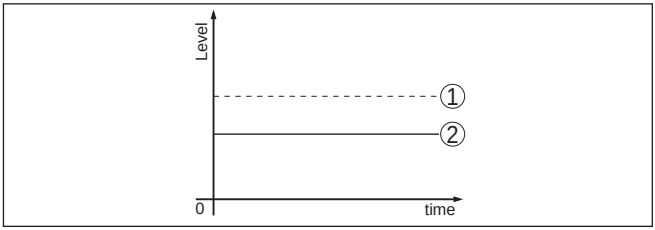
Further comprehensive diagnostics options are available with a PC with PACTware and the suitable DTM. In many cases, the reasons can be determined in this way and faults rectified.

**Treatment of measurement errors with bulk solids**

The below tables show typical examples for application-relevant measurement errors with bulk solids. There are two measurement errors:

- Constant level
- Filling
- Emptying

The images in column "*Error pattern*" show the real level with a broken line and the level displayed by the sensor as a continuous line.

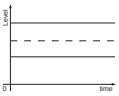
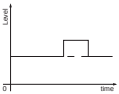



*1 Real level*
*2 Level displayed by the sensor*

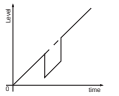
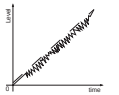
Notes:

- Wherever the sensor displays a constant value, the reason could also be the fault setting of the current output to "Hold value"
- In case of a too low level indication, the reason could be a line resistance that is too high

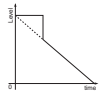
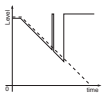
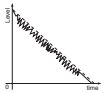
### Measurement error with constant level

| Fault description | Error pattern | Cause | Rectification |
|---|---|---|---|
| 1. Measured value shows a too low or too high level |  | – Min./max. adjustment not correct | – Adapt min./max. adjustment |
| | | – Wrong linearization curve | – Adapt linearization curve |
| 2. Measured value jumps towards 100 % |  | – Due to the process, the amplitude of the product echo sinks<br>– A false signal suppression was not carried out | – Carry out a false signal suppression |
| | | – Amplitude or position of a false echo has changed (e.g. condensation, buildup); false signal suppression no longer matches | – Determine the reason for the changed false echoes, carry out false signal suppression, e.g. with condensation |

### Measurement error during filling

| Fault description | Error pattern | Cause | Rectification |
|---|---|---|---|
| 3. Measured value jumps towards 0 % during filling |  | – Amplitude of a multiple echo (vessel top - product surface) is larger than the level echo | – Check parameter "Application", especially vessel top, type of medium, dished end, high dielectric constant, adapt if necessary |
| | | – The level echo cannot be distinguished from the false echo at a false echo position (jumps to multiple echo) | – Remove/reduce false echo: minimize interfering installations by changing the polarization direction<br>– Chose a more suitable installation position |
| | | – Transverse reflection from an extraction funnel, amplitude of the transverse reflection larger than the level echo | – Direct sensor to the opposite funnel wall, avoid crossing with the filling stream |
| 4. Measured value fluctuates around 10 … 20 % |  | – Various echoes from an uneven product surface, e.g. a material cone | – Check parameter "Type of medium" and adapt, if necessary<br>– Optimize installation position and sensor orientation |
| | | – Reflections from the product surface via the vessel wall (deflection) | – Select a more suitable installation position, optimize sensor orientation, e.g. with a swivelling holder |
| 5. Measured value jumps sporadically to 100 % during filling | | – Changing condensation or contamination on the antenna | – Carry out a false signal suppression or increase false signal suppression with condensation/contamination in the close range by editing<br>– With bulk solids use radar sensor with purging air connection or flexible antenna cover |

**Measurement error during emptying**

| Fault description | Error pattern | Cause | Rectification |
|---|---|---|---|
| 6. Measured value remains unchanged in the close range during emptying |  | – False echo larger than the level echo<br>– Level echo too small | – Remove false echoes in the close range. Check: Antenna must protrude out of the socket<br>– Remove contamination on the antenna<br>– Minimize interfering installations in the close range by changing the polarization direction<br>– After removing the false echoes, the false signal suppression must be deleted. Carry out a new false signal suppression |
| 7. Measured value jumps sporadically towards 100 % during emptying |  | – Changing condensation or contamination on the antenna | – Carry out false signal suppression or increase false signal suppression in the close range by editing<br>– With bulk solids use radar sensor with purging air connection or flexible antenna cover |
| 8. Measured value fluctuates around 10 … 20 % |  | – Various echoes from an uneven product surface, e.g. an extraction funnel<br>– Reflections from the product surface via the vessel wall (deflection) | – Check parameter "Type of medium" and adapt, if necessary<br>– Optimize installation position and sensor orientation |

**Reaction after fault rectification**

Depending on the reason for the fault and the measures taken, the steps described in chapter "*Setup*" must be carried out again or must be checked for plausibility and completeness.

**24 hour service hotline**

Should these measures not be successful, please call in urgent cases the VEGA service hotline under the phone no. **+49 1805 858550**.

The hotline is also available outside normal working hours, seven days a week around the clock.

Since we offer this service worldwide, the support is provided in English. The service itself is free of charge, the only costs involved are the normal call charges.

## 9.5 Exchanging the electronics module

If the electronics module is defective, it can be replaced by the user.

In Ex applications, only instruments and electronics modules with appropriate Ex approval may be used.

If there is no electronics module available on site, the electronics module can be ordered through the agency serving you. The electronics modules are adapted to the respective sensor and differ in signal output or voltage supply.

The new electronics module must be loaded with the default settings of the sensor. These are the options:

- In the factory
- Or on site by the user

In both cases, the serial number of the sensor is needed. The serial numbers are stated on the type label of the instrument, on the inside of the housing as well as on the delivery note.

When loading on site, first of all the order data must be downloaded from the Internet (see operating instructions manual "*Electronics module*").

## 9.6 Software update

The following components are required to update the sensor software:

- Sensor
- Voltage supply
- Interface adapter VEGACONNECT
- PC with PACTware
- Current sensor software as file

You can find the actual sensor software as well as detailed information of the procedure under "www.vega.com/downloads" and "*Software*".

You can find information about the installation in the download file.

**Caution:**
Instruments with approvals can be bound to certain software versions. Therefore make sure that the approval remains effective with a software update.

You can find detailed information on www.vega.com/downloads and "*Approvals*".

## 9.7 How to proceed if a repair is needed

You can find a repair form as well as detailed information on how to proceed under www.vega.com/downloads and "*Forms and certificates*".

By doing this you help us carry out the repair quickly and without having to call back for needed information.

If a repair is necessary, please proceed as follows:

- Print and fill out one form per instrument
- Clean the instrument and pack it damage-proof
- Attach the completed form and, if need be, also a safety data sheet outside on the packaging
- Please contact the agency serving you to get the address for the return shipment. You can find the agency on our home page www.vega.com.

# 10 Dismounting

## 10.1 Dismounting steps

**Warning:**
Before dismounting, be aware of dangerous process conditions such as e.g. pressure in the vessel or pipeline, high temperatures, corrosive or toxic products etc.

Take note of chapters "*Mounting*" and "*Connecting to power supply*" and carry out the listed steps in reverse order.

## 10.2 Disposal

The instrument consists of materials which can be recycled by specialised recycling companies. We use recyclable materials and have designed the parts to be easily separable.

Correct disposal avoids negative effects on humans and the environment and ensures recycling of useful raw materials.

Materials: see chapter "*Technical data*"

If you have no way to dispose of the old instrument properly, please contact us concerning return and disposal.

**WEEE directive 2002/96/EG**
This instrument is not subject to the WEEE directive 2002/96/EG and the respective national laws. Pass the instrument directly on to a specialised recycling company and do not use the municipal collecting points. These may be used only for privately used products according to the WEEE directive.

# 11 Supplement

## 11.1 Technical data

**General data**

| | |
|---|---|
| 316L corresponds to 1.4404 or 1.4435 | |
| Materials, wetted parts | |
| – Process fitting | 316L, Hastelloy C22, Monell Alloy |
| – Process seal | On site (instruments with thread: Klingersil C-4400 is attached) |
| – Antenna | 316L, Hastelloy C22, Tantalum, 316L electropolished, stainless steel investment casting 1.4848, Monell Alloy, 316L Safecoat coated |
| – Antenna impedance cone | PTFE TFM 1600 or PTFE INOFLON M290, PP, PEEK, ceramic (99.7 % $Al_2O_3$) |
| – seal, antenna system | FKM (SHS FPM 70C3 GLT), FFKM (Kalrez 6375), FFKM (Kalrez 2035), FFKM (Kalrez 6230 - FDA), graphite (99.9 %) |
| Materials, non-wetted parts | |
| – Plastic housing | plastic PBT (Polyester) |
| – Aluminium die-casting housing | Aluminium die-casting AlSi10Mg, powder-coated - basis: Polyester |
| – Stainless steel housing | 316L |
| – Seal between housing and housing cover | NBR (stainless steel housing, precision casting), silicone (aluminium/plastic housing; stainless steel housing, electropolished) |
| – Inspection window in housing cover (optional) | Polycarbonate |
| – Ground terminal | 316L |
| Ohmic contact | Between ground terminal, process fitting and antenna |
| Process fittings | |
| – Pipe thread, cylindrical (ISO 228 T1) | G1½ according to DIN 3852-A |
| – American pipe thread, tapered | 1½ NPT, 2 NPT |
| – Flanges | DIN from DN 25, ANSI from 1" |
| Weights | |
| – Instrument (depending on housing, process fitting and antenna) | approx. 2 … 17.2 kg (4.409 … 37.92 lbs) |
| – Antenna extension | 1.6 kg/m (1.157 lbs/ft) |
| Length antenna extension max. | 5.85 m (19.19 ft) |
| Torque for NPT cable glands and Conduit tubes | |
| – Plastic housing | max. 10 Nm (7.376 lbf ft) |
| – Aluminium/Stainless steel housing | max. 50 Nm (36.88 lbf ft) |

## Input variable

| | |
|---|---|
| Measured variable | The measured quantity is the distance between process fitting of the sensor and product surface. The reference plane is the seal surface on the hexagon or the lower side of the flange. |

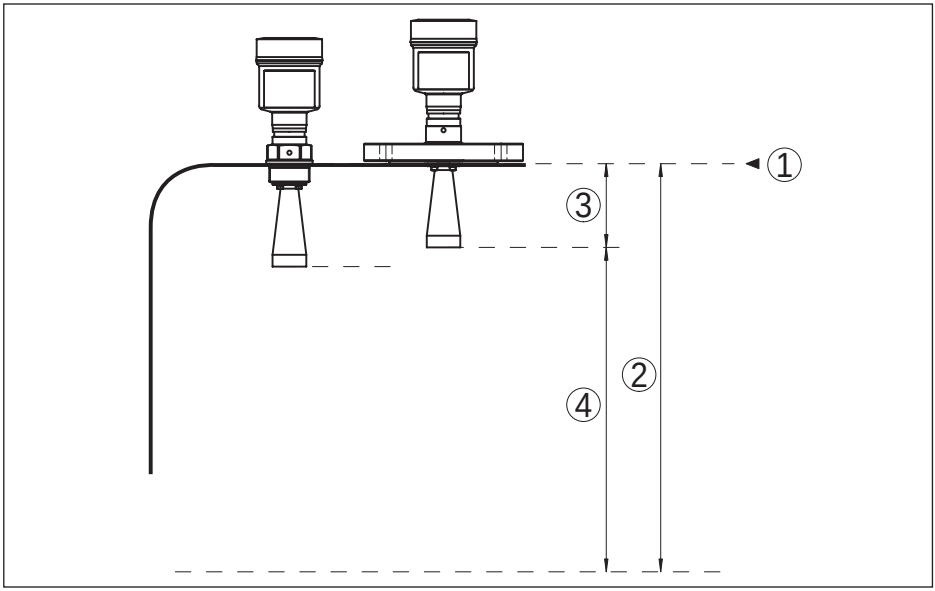



*Fig. 53: Data of the input variable*

*1 Reference plane*
*2 Measured variable, max. measuring range*
*3 Antenna length*
*4 Useful measuring range*

| | |
|---|---|
| Max. measuring range | 75 m (246.1 ft) |
| Recommended meas. range depending on the antenna diameter | |
| – ø 40 mm (1.575 in) | up to 15 m (49.21 ft) |
| – ø 48 mm (1.89 in) | up to 20 m (65.62 ft) |
| – ø 75 mm (2.953 in) | up to 40 m (131.2 ft) |
| – ø 95 mm (3.74 in) | up to 50 m (164 ft) |
| – Parabolic antenna | up to 75 m (246.1 ft) |

## Output variable

| | |
|---|---|
| Output signal | digital output signal, format according to IEEE-754 |
| Sensor address | 126 (default setting) |
| Damping (63 % of the input variable) | 0 … 999 s, adjustable |
| Profibus PA profile | 3.02 |
| Number of FBs with AI (function blocks with analogue input) | 3 |

| | |
|---|---|
| Default values | |
| – 1. FB | PV |
| – 2. FB | SV 1 |
| – 3. FB | SV 2 |
| Current value | |
| – Non-Ex and Ex ia instrument | 10 mA, ±0.5 mA |
| – Ex-d instruments | 16 mA, ±0.5 mA |
| Resolution, digital | < 1 mm (0.039 in) |

**Accuracy (according to DIN EN 60770-1)**

| | |
|---|---|
| Process reference conditions according to DIN EN 61298-1 | |
| – Temperature | +18 … +30 °C (+64 … +86 °F) |
| – Relative humidity | 45 … 75 % |
| – Air pressure | 860 … 1060 mbar/86 … 106 kPa (12.5 … 15.4 psig) |
| Installation reference conditions | |
| – Min. distance to installations | > 200 mm (7.874 in) |
| – Reflector | Plane plate reflector |
| – False reflections | Biggest false signal, 20 dB smaller than the useful signal |
| Deviation with liquids | See following diagrams |

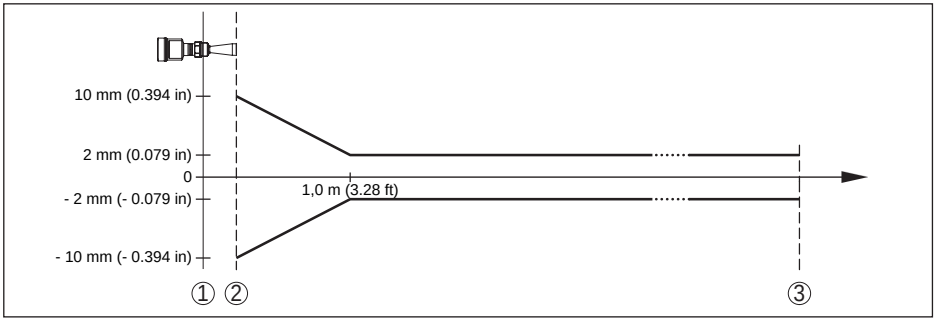



*Fig. 54: Deviation under reference conditions*

*1 Reference plane*
*2 Antenna edge*
*3 Recommended measuring range*

| | |
|---|---|
| Repeatability | ≤ ±1 mm |
| Deviation with bulk solids | The values depend to a great extent on the application. Binding specifications are thus not possible. |
| Deviation under EMC influence | ≤ ±30 mm |

**Variables influencing measurement accuracy**

| | |
|---|---|
| Temperature drift - Digital output | ±3 mm/10 K relating to the max. measuring range or max. 10 mm |

| | |
|---|---|
| Additional deviation through electromagnetic interference acc. to EN 61326 | < ±50 mm |

## Characteristics and performance data

| | |
|---|---|
| Measuring frequency | K-band (26 GHz technology) |
| Measuring cycle time approx. | 700 ms |
| Step response time[1] | ≤ 3 s |
| Beam angle[2] | |
| – Horn antenna ø 40 mm (1.575 in) | 20° |
| – Horn antenna ø 48 mm (1.89 in) | 15° |
| – Horn antenna ø 75 mm (2.953 in) | 10° |
| – Horn antenna ø 95 mm (3.74 in) | 8° |
| – Parabolic antenna | 3° |
| Emitted HF power (depending on the parameter adjustment)[3] | |
| – Average spectral transmission power density | -14 dBm/MHz EIRP |
| – Max. spectral transmission power density | +43 dBm/50 MHz EIRP |
| – Max. power density in a distance of 1 m | < 1 µW/cm² |

## Ambient conditions

| | |
|---|---|
| Ambient, storage and transport temperature | -40 … +80 °C (-40 … +176 °F) |

## Process conditions

For the process conditions, please also note the specifications on the type label. The lowest value always applies.

| Seal | Antenna impedance cone | Process temperature (measured on the process fitting) |
|---|---|---|
| FKM (SHS FPM 70C3 GLT) | PTFE | -40 … +130 °C (-40 … +266 °F) |
| | PTFE[4] | -40 … +200 °C (-40 … +392 °F) |
| | PEEK[5] | -40 … +200 °C (-40 … +392 °F) |
| FFKM (Kalrez 6375) | PTFE | -20 … +130 °C (-4 … +266 °F) |
| | PEEK | -20 … +250 °C (-4 … +482 °F) |
| FFKM (Kalrez 2035) | PTFE | -15 … +130 °C (5 … +266 °F) |
| | PEEK | -15 … +210 °C (5 … +410 °F) |

[1] Time span after a sudden measuring distance change by max. 0.5 m in liquid applications, max 2 m with bulk solids applications, until the output signal has taken for the first time 90 % of the final value (IEC 61298-2).
[2] Outside the specified beam angle, the energy of the radar signal has a level which is reduced by 50 % (-3 dB)
[3] EIRP: Equivalent Isotropic Radiated Power
[4] Not with steam
[5] Not with steam

| Seal | Antenna impedance cone | Process temperature (measured on the process fitting) |
|---|---|---|
| FFKM (Kalrez 6230) | PTFE | -15 … +130 °C (5 … +266 °F) |
| | PEEK | -15 … +250 °C (5 … +482 °F) |
| Graphite | Ceramic | -196 … +450 °C (-321 … +842 °F) |
| Graphite (process fitting Hastelloy C 22) | Ceramic | -196 … +400 °C (-321 … +752 °F) |

Vessel pressure - horn antenna

- Antenna impedance cone PTFE: -1 … 40 bar (-100 … 4000 kPa/-14.5 … 580 psig)
- Antenna impedance cone PP: -1 … 3 bar (-100 … 300 kPa/-14.5 … 43.5 psig)
- Antenna impedance cone PEEK: -1 … 100 bar (-100 … 10000 kPa/-14.5 … 1450 psig)
- Antenna impedance cone ceramic: -1 … 160 bar (-100 … 16000 kPa/-14.5 … 2320 psig)

Vessel pressure - parabolic antenna: -1 … 6 bar (-100 … 6000 kPa/-14.5 … 870 psig)

Vessel pressure with swivelling holder: -1 … 1 bar (-100 … 100 kPa/-14.5 … 14.5 psig)

Vessel pressure relating to the flange nominal stage: see supplementary instructions manual "*Flanges according to DIN-EN-ASME-JIS*"

Vibration resistance

- Horn antenna: 4 g at 5 … 200 Hz according to EN 60068-2-6 (vibration with resonance)
- Parabolic antenna: 1 g at 5 … 200 Hz according to EN 60068-2-6 (vibration with resonance)

Shock resistance

- Horn antenna: 100 g, 6 ms according to EN 60068-2-27 (mechanical shock)
- Parabolic antenna: 25 g, 6 ms according to EN 60068-2-27 (mechanical shock)

## Data on rinsing air connection

Max. permissible pressure: 6 bar (87.02 psig)

Air volume with horn antenna, depending on pressure (recommended area)

| Pressure | Without reflux valve | With reflux valve |
|---|---|---|
| 0.5 bar (7.25 psig) | 3.3 m³/h | 1.2 m³/h |
| 0.6 bar (8.70 psig) | 3.5 m³/h | 1.4 m³/h |
| 0.7 bar (10.15 psig) | 3.7 m³/h | 1.7 m³/h |
| 0.8 bar (11.60 psig) | 3.9 m³/h | 1.8 m³/h |
| 0.9 bar (13.05 psig) | 4.0 m³/h | 2.1 m³/h |
| 1 bar (14.5 psig) | 4.2 m³/h | 2.2 m³/h |
| 1.5 bar (21.76 psig) | 5.0 m³/h | 3.2 m³/h |
| 2 bar (29.0 psig) | 5.5 m³/h | 4.5 m³/h |

Air volume with parabolic antenna, depending on pressure (recommended area)

| Pressure | Without reflux valve | With reflux valve |
|---|---|---|
| 0.5 bar (7.25 psig) | 3.0 m³/h | 1.2 m³/h |
| 0.6 bar (8.70 psig) | 3.2 m³/h | 1.4 m³/h |
| 0.7 bar (10.15 psig) | 3.4 m³/h | 1.7 m³/h |
| 0.8 bar (11.60 psig) | 3.5 m³/h | 1.9 m³/h |
| 0.9 bar (13.05 psig) | 3.6 m³/h | 2.0 m³/h |
| 1 bar (14.5 psig) | 3.8 m³/h | 2.2 m³/h |
| 1.5 bar (21.76 psig) | 4.3 m³/h | 3.5 m³/h |
| 2 bar (29.0 psig) | 4.8 m³/h | 4.0 m³/h |

Thread G⅛

Closure with

- Non-Ex: Dust protection cover of PE
- Ex: Threaded plug of 316Ti

Reflux valve - unmounted (as option with non-Ex version, included in the scope of delivery with Ex version)

- Material: 316Ti
- Seal: FKM (SHS FPM 70C3 GLT), FFKM (Kalrez 6375)
- for tube diameter: 6 mm
- opening pressure: 0.5 bar (7.25 psig)
- Nominal pressure stage: PN 250

**Electromechanical data - version IP 66/IP 67 and IP 66/IP 68; 0.2 bar**

Options of the cable entry

- Cable gland: M20 x 1.5 (cable: ø 5 … 9 mm)
- Cable entry: ½ NPT
- Blind plug: M20 x 1.5; ½ NPT
- Closing cap: M20 x 1.5; ½ NPT

Plug options

- Signal circuit: Plug M12 x 1, according to ISO 4400, Harting HAN, 7/8" FF
- Indication circuit: M12 x 1 plug

Wire cross-section (spring-loaded terminals)

- Massive wire, cord: 0.2 … 2.5 mm² (AWG 24 … 14)
- Stranded wire with end sleeve: 0.2 … 1.5 mm² (AWG 24 … 16)

**Electromechanical data - version IP 66/IP 68 (1 bar)**

Options of the cable entry

- Cable gland with integrated connection cable: M20 x 1.5 (cable: ø 5 … 9 mm)
- Cable entry: ½ NPT
- Blind plug: M20 x 1.5; ½ NPT

| | |
|---|---|
| Connection cable | |
| – Wire cross-section | 0.5 mm² (AWG 20) |
| – Wire resistance | < 0.036 Ω/m |
| – Tensile strength | < 1200 N (270 lbf) |
| – Standard length | 5 m (16.4 ft) |
| – Max. length | 180 m (590.6 ft) |
| – Min. bending radius | 25 mm (0.984 in) with 25 °C (77 °F) |
| – Diameter approx. | 8 mm (0.315 in) |
| – Colour - Non-Ex version | Black |
| – Colour - Ex-version | Blue |

**Display and adjustment module**

| | |
|---|---|
| Display element | Display with backlight |
| Measured value indication | |
| – Number of digits | 5 |
| – Size of digits | W x H = 7 x 13 mm |
| Adjustment elements | 4 keys |
| Protection rating | |
| – unassembled | IP 20 |
| – mounted into the housing without cover | IP 40 |
| Materials | |
| – Housing | ABS |
| – Inspection window | Polyester foil |

**Interface to the external display and adjustment unit**

| | |
|---|---|
| Data transmission | digital ($I^2C$-Bus) |
| Configuration, connection cable | 4-wire, screened |
| Cable length max. | 25 m |

**Integrated clock**

| | |
|---|---|
| Date format | Day.Month.Year |
| Time format | 12 h/24 h |
| Time zone Ex factory | CET |
| Rate deviation max. | 10.5 min/year |

**Measurement electronics temerature**

| | |
|---|---|
| Resolution | 1 °C (1.8 °F) |
| Accuracy | ±1 °C (1.8 °F) |

**Voltage supply**

| | |
|---|---|
| Operating voltage | |
| – Non-Ex instrument | 9 … 32 V DC |

- Ex-ia instrument - Power supply FISCO model: 9 … 17.5 V DC
- Ex-ia instrument - Power supply ENTITY model: 9 … 24 V DC
- Ex-d-ia instrument: 14 … 32 V DC

Number of sensors per DP/PA segment coupler, max.

- Non-Ex: 32
- Ex: 10

## Electrical protective measures

Protection rating

| Housing material | Version | IP-protection class | NEMA protection |
|---|---|---|---|
| Plastic | Single chamber | IP 66/IP 67 | NEMA 4X |
| | Double chamber | IP 66/IP 67 | NEMA 4X |
| Aluminium | Single chamber | IP 66/IP 68 (0.2 bar)<br>IP 68 (1 bar) | NEMA 6P<br>NEMA 6P |
| | Double chamber | IP 66/IP 67<br>IP 66/IP 68 (0.2 bar)<br>IP 68 (1 bar) | NEMA 4X<br>NEMA 6P<br>NEMA 6P |
| Stainless steel, electro-polished | Single chamber | IP 66/IP 68 (0.2 bar) | NEMA 6P |
| Stainless steel, investment casting | Single chamber | IP 66/IP 68 (0.2 bar)<br>IP 68 (1 bar) | NEMA 6P<br>NEMA 6P |
| | Double chamber | IP 66/IP 67<br>IP 66/IP 68 (0.2 bar)<br>IP 68 (1 bar) | NEMA 4X<br>NEMA 6P<br>NEMA 6P |

Overvoltage category: III

Protection class: III

## Approvals

Instruments with approvals can have different technical data depending on the version.

For that reason the associated approval documents of these instruments have to be carefully noted. They are part of the delivery or can be downloaded under www.vega.com, "*VEGA Tools*" and "*Instrument search*" as well as via www.vega.com/downloads and "*Approvals*".

## Overvoltage protection

Max. permissible current per circuit: 0.6 A

$R_i$ per circuit: < 3.6 Ω

$L_i$ per circuit: 0 mH

$C_i$ per circuit: 0 nF

Response voltage: 41 V DC

Response time: < $10^{-11}$ s

Nominal leakage current < 10 kA (8/20 µs)

## 11.2 Communication Profibus PA

### Instrument master file

The instrument master file (GSD) contains the characteristic data of the Profibus PA instrument. These data are, e.g. the permissible transmission rates as well as information on diagnostics values and the format of the measured value outputted by the PA instrument.

A bitmap file is also provided for the Profibus network planning tool. This file is installed automatically when the GSD file is integrated. The bitmap file is used for symbolic indication of the PA instrument in the configuration tool.

### ID number

Each Profibus instrument gets an unambiguous ident number (ID number) from the Profibus user organisation (PNO). This ID number is also included in the name of the GSD file. Optionally to this manufacturer-specific GSD file, PNO provides also a general so-called profile-specific GSD file. If the general GSD file is used, the sensor must be set to the profile-specific ident number via the DTM software. By default, the sensor operates with the manufacturer-specific ID number. When using the instruments on a segment coupler SK-2 or SK-3, no special GSD files are required.

The following table shows the instrument ID and the GSD file names for VEGAPULS radar sensors.

| Device name | Instrument ID | | GSD file name | |
|---|---|---|---|---|
| | VEGA | Instrument class in profile 3.02 | VEGA | Profile-specific |
| VEGAPULS WL 61 | 0x0CDB | 0x9702 | PS61WL0CDB.GSD | PA139702.GSD |
| VEGAPULS 61 | 0x0BFC | 0x9702 | PS610BFC.GSD | PA139702.GSD |
| VEGAPULS 62 | 0x0BFD | 0x9702 | PS620BFD.GSD | PA139702.GSD |
| VEGAPULS 63 | 0x0BFE | 0x9702 | PS630BFE.GSD | PA139702.GSD |
| VEGAPULS 65 | 0x0BFF | 0x9702 | PS650BFF.GSD | PA139702.GSD |
| VEGAPULS 66 | 0x0C00 | 0x9702 | PS660C00.GSD | PA139702.GSD |
| VEGAPULS 67 | 0x0C01 | 0x9702 | PS670C01.GSD | PA139702.GSD |
| VEGAPULS SR 68 | 0x0CDC | 0x9702 | PS68R0CDC.GSD | PA139702.GSD |
| VEGAPULS 68 | 0x0C02 | 0x9702 | PS680C02.GSD | PA139702.GSD |

### Cyclical data traffic

The master class 1 (e.g. PLC) cyclically reads out measured values from the sensor during operation. The below block diagram below shows which data can be accessed by the PLC.

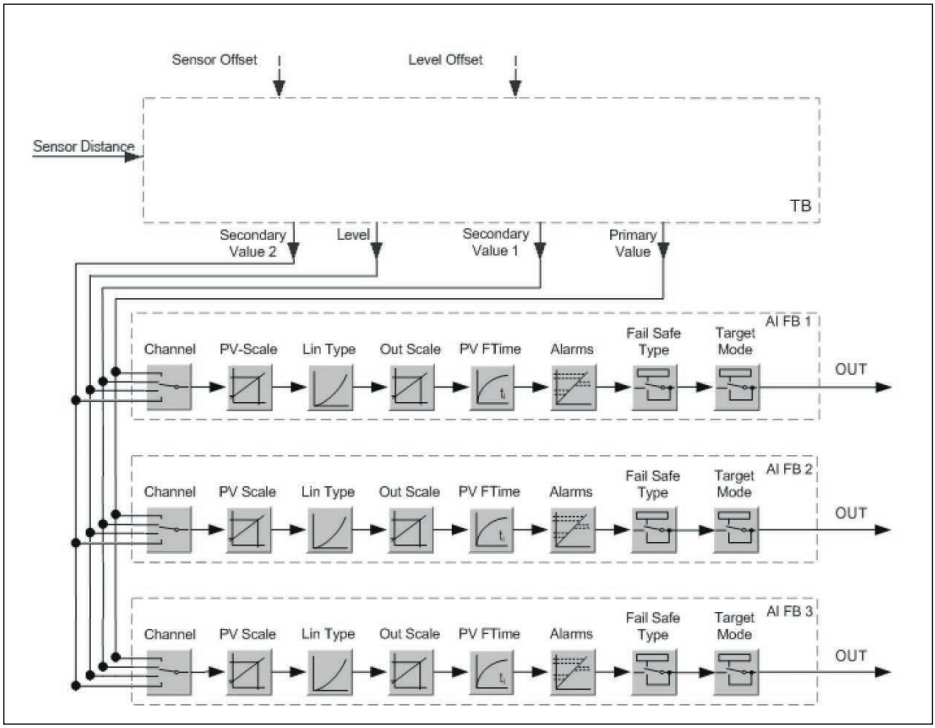



*Fig. 55: VEGAPULS 68: Block diagram with AI FB 1 … AI FB 3 OUT values*

*TB Transducer Block*
*FB 1 … FB 3 Function Block*

## Module of the PA sensors

For the cyclic data traffic, VEGAPULS 68 provides the following modules:

- AI FB1 (OUT)
  - Out value of the AI FB1 after scaling
- AI FB2 (OUT)
  - Out value of the AI FB2 after scaling
- AI FB3 (OUT)
  - Out value of the AI FB3 after scaling
- Free Place
  - This module must be used if a value in the data telegram of the cyclical data traffic should not be used (e.g. replacement of temperature and Additional Cyclic Value)

A maximum of three modules can be active. By means of the configuration software of the Profibus master you can determine the configuration of the cyclical data telegram with these modules. The procedure depends on the respective configuration software.

**Note:**
The modules are available in two versions:

- Short for Profibus master supporting only one "Identifier Format" byte, e.g. Allen Bradley

- Long for Profibus master only supporting the "Identifier Format" byte, e.g. Siemens S7-300/400

## Examples of telegram configuration

In the following you will see how the modules can be combined and how the appendant data telegram is structured.

**Example 1**

- AI FB1 (OUT)
- AI FB2 (OUT)
- AI FB3 (OUT)

| **Byte-No.** | **1** | **2** | **3** | **4** | **5** | **6** | **7** | **8** | **9** | **10** | **11** | **12** | **13** | **14** | **15** |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| Format | IEEE-754-Floating point value | | | | Status | IEEE-754-Floating point value | | | | Status | IEEE-754-Floating point value | | | | Status |
| Value | AI FB1 (OUT) | | | | AI FB1 | AI FB2 (OUT) | | | | AI FB2 | AI FB3 (OUT) | | | | AI FB3 |

**Example 2**

- AI FB1 (OUT)
- Free Place
- Free Place

| **Byte-No.** | **1** | **2** | **3** | **4** | **5** |
|---|---|---|---|---|---|
| Format | IEEE-754-Floating point value | | | | Status |
| Value | AI FB1 (OUT) | | | | AI FB1 |

**Note:**
Bytes 6-15 are not used in this example.

## Data format of the output signal

| Byte4 | Byte3 | Byte2 | Byte1 | Byte0 |
|---|---|---|---|---|
| Status | Value (IEEE-754) | | | |

*Fig. 56: Data format of the output signal*

The status byte corresponds to profile 3.02 "Profibus PA Profile for Process Control Devices" coded. The status "Measured value OK" is coded as 80 (hex) (Bit7 = 1, Bit6 … 0 = 0).

The measured value is transferred as a 32 bit floating point number in the IEEE-754 format.

| Byte n | | | | | | | | Byte n+1 | | | | | | | | Byte n+2 | | | | | | | | Byte n+3 | | | | | | | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| VZ | $2^7$ | $2^6$ | $2^5$ | $2^4$ | $2^3$ | $2^2$ | $2^1$ | $2^0$ | $2^{-1}$ | $2^{-2}$ | $2^{-3}$ | $2^{-4}$ | $2^{-5}$ | $2^{-6}$ | $2^{-7}$ | $2^{-8}$ | $2^{-9}$ | $2^{-10}$ | $2^{-11}$ | $2^{-12}$ | $2^{-13}$ | $2^{-14}$ | $2^{-15}$ | $2^{-16}$ | $2^{-17}$ | $2^{-18}$ | $2^{-19}$ | $2^{-20}$ | $2^{-21}$ | $2^{-22}$ | $2^{-23}$ |
| Sign Bit | Exponent | | | | | | | Significant | | | | | | | | Significant | | | | | | | | Significant | | | | | | | |

$$\text{Value} = (-1)^{VZ} \bullet 2^{(\text{Exponent} - 127)} \bullet (1 + \text{Significant})$$

*Fig. 57: Data format of the measured value*

## Coding of the status byte associated with the PA output value

You can find further information for the coding of the status byte in the Device Description 3.02 on www.profibus.com.

| Status code | Description according to Profibus standard | Possible cause |
|---|---|---|
| 0 x 00 | bad - non-specific | Flash-Update active |
| 0 x 04 | bad - configuration error | – Adjustment error<br>– Configuration error with PV-Scale (PV-Span too small)<br>– Unit irregularity<br>– Error in the linearization table |
| 0 x 0C | bad - sensor failure | – Hardware error<br>– Converter error<br>– Leakage pulse error<br>– Trigger error |
| 0 x 10 | bad - sensor failure | – Measured value generation error<br>– Temperature measurement error |
| 0 x 1f | bad - out of service constant | "Out of Service" mode switched on |
| 0 x 44 | uncertain - last unstable value | Failsafe replacement value (Failsafe-Mode = "Last value" and already valid measured value since switching on) |
| 0 x 48 | uncertain substitute set | – Switch on simulation<br>– Failsafe replacement value (Failsafe-Mode = "Fsafe value") |
| 0 x 4c | uncertain - initial value | Failsafe replacement value (Failsafe-Mode = "Last valid value" and no valid measured value since switching on) |
| 0 x 51 | uncertain - sensor; conversion not accurate - low limited | Sensor value < lower limit |
| 0 x 52 | uncertain - sensor; conversion not accurate - high limited | Sensor value > upper limit |
| 0 x 80 | good (non-cascade) - OK | OK |
| 0 x 84 | good (non-cascade) - active block alarm | Static revision (FB, TB) changed (10 sec. active, after the parameter of the static category has been written) |
| 0 x 89 | good (non-cascade) - active advisory alarm - low limited | Lo-Alarm |
| 0 x 8a | good (non-cascade) - active advisory alarm - high limited | Hi-Alarm |
| 0 x 8d | good (non-cascade) - active critical alarm - low limited | Lo-Lo-Alarm |
| 0 x 8e | good (non-cascade) - active critical alarm - high limited | Hi-Hi-Alarm |

## 11.3 Dimensions

The following dimensional drawings represent only an extract of all possible versions. Detailed dimensional drawings can be downloaded at www.vega.com/downloads under "*Drawings*".

### Plastic housing

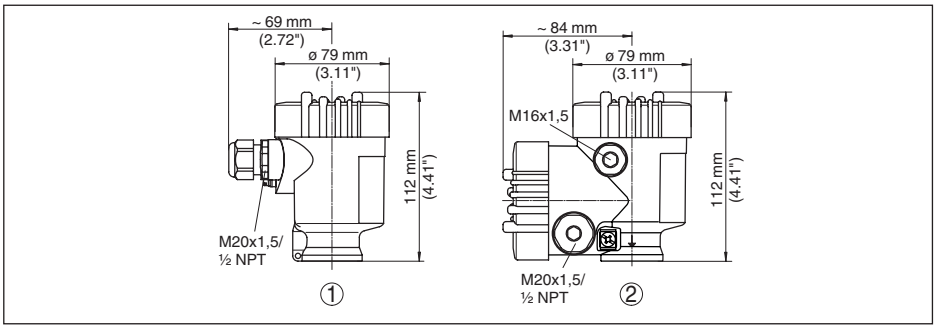



*Fig. 58: Housing versions in protection IP 66/IP 68 (0.2 bar) - with integrated display and adjustment module the housing is 9 mm/0.35 in higher*

*1 Single chamber version*
*2 Double chamber version*

### Aluminium housing

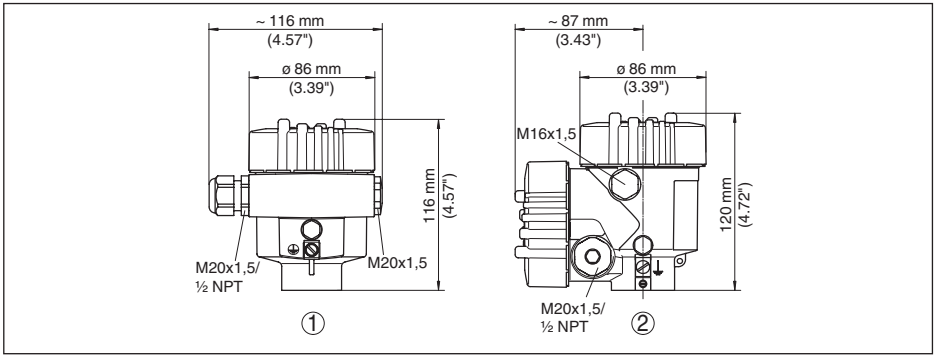



*Fig. 59: Housing versions in protection IP 66/IP 68 (0.2 bar) - with integrated display and adjustment module the housing is 9 mm/0.35 in higher*

*1 Single chamber version*
*2 Double chamber version*

## Aluminium housing in protection rating IP 66/IP 68 (1 bar)

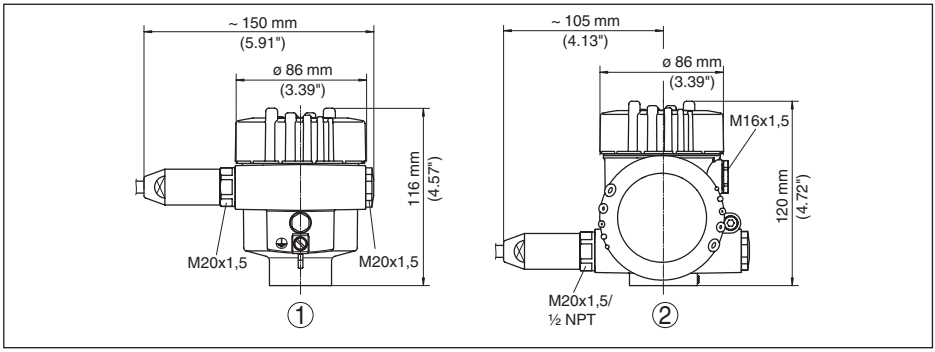



*Fig. 60: Housing versions in protection IP66/IP68 (1 bar) - with integrated display and adjustment module the housing is 9 mm/0.35 in higher*

*1 Single chamber version*
*2 Double chamber version*

## Stainless steel housing

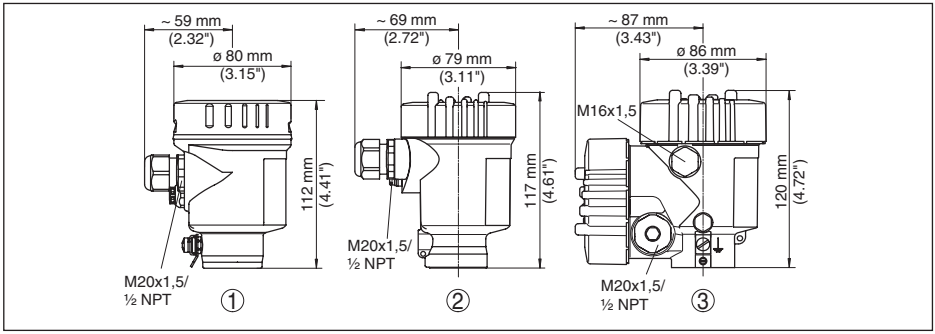



*Fig. 61: Housing versions in protection IP 66/IP 68 (0.2 bar) - with integrated display and adjustment module the housing is 9 mm/0.35 in higher*

*1 Single chamber version, electropolished*
*2 Single chamber version, precision casting*
*3 Double chamber version, precision casting*

## Stainless steel housing in protection rating IP 66/IP 68, 1 bar

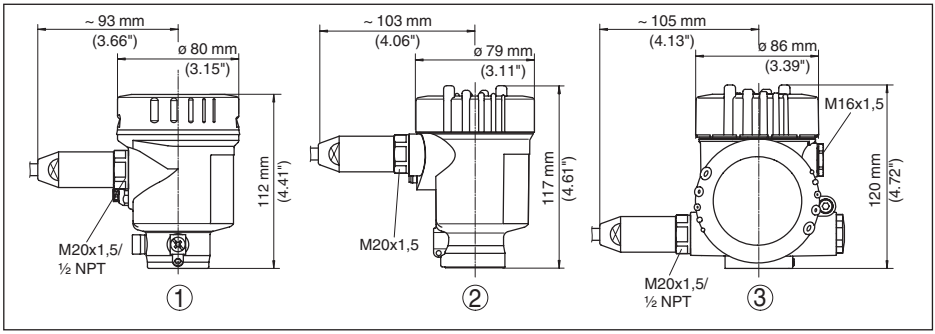
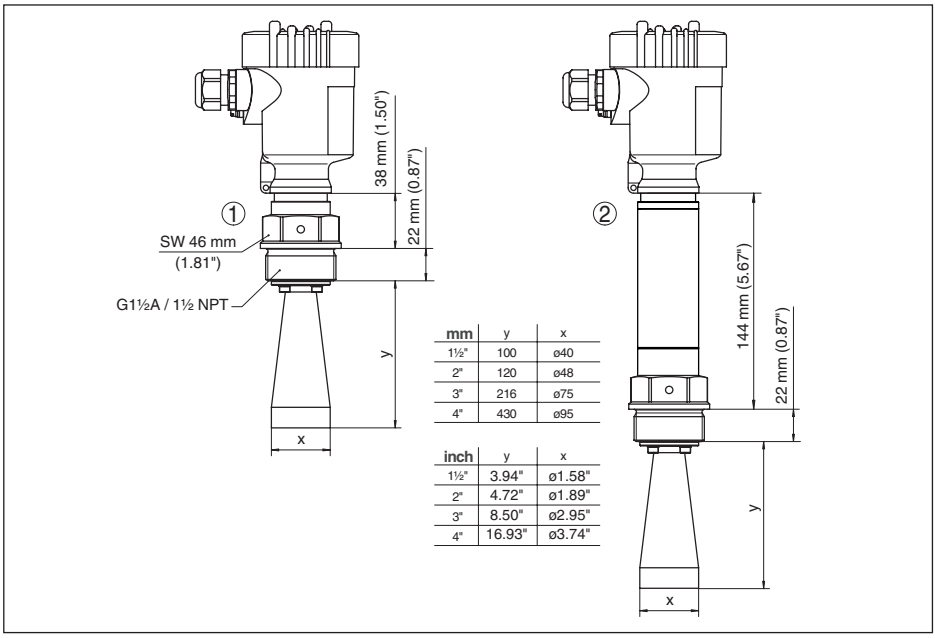



*Fig. 62: Housing versions in protection IP66/IP68 (1 bar) - with integrated display and adjustment module the housing is 9 mm/0.35 in higher*

1 *Single chamber version, electropolished*
2 *Single chamber version, precision casting*
3 *Double chamber version, precision casting*

## VEGAPULS 68, horn antenna in threaded version



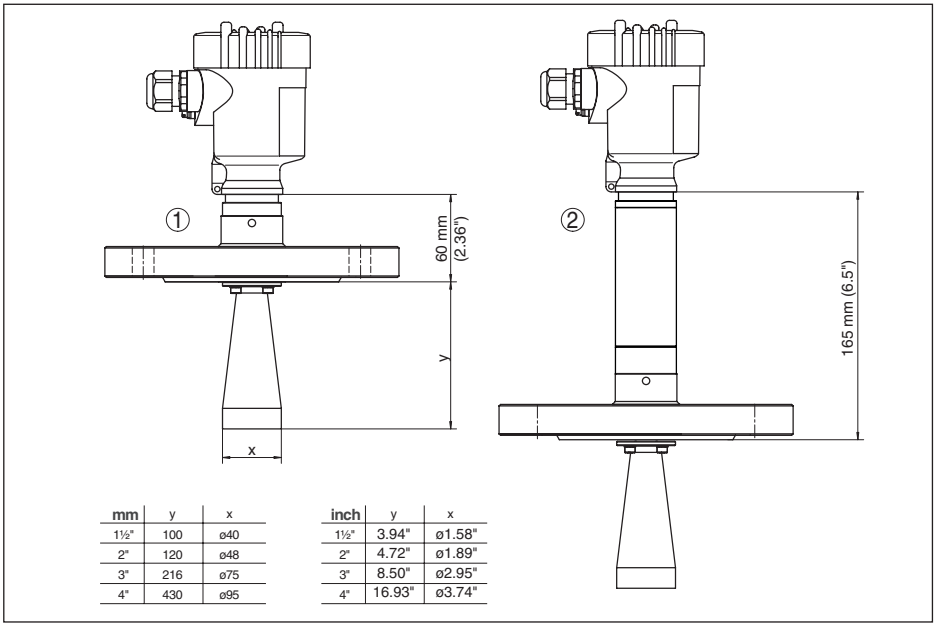

| mm | y | x |
|---|---|---|
| 1½" | 100 | ø40 |
| 2" | 120 | ø48 |
| 3" | 216 | ø75 |
| 4" | 430 | ø95 |

| inch | y | x |
|---|---|---|
| 1½" | 3.94" | ø1.58" |
| 2" | 4.72" | ø1.89" |
| 3" | 8.50" | ø2.95" |
| 4" | 16.93" | ø3.74" |

*Fig. 63: VEGAPULS 68, horn antenna in threaded version*

1 *Standard*
2 *With temperature adapter up to 250 °C*

## VEGAPULS 68, horn antenna in flange version



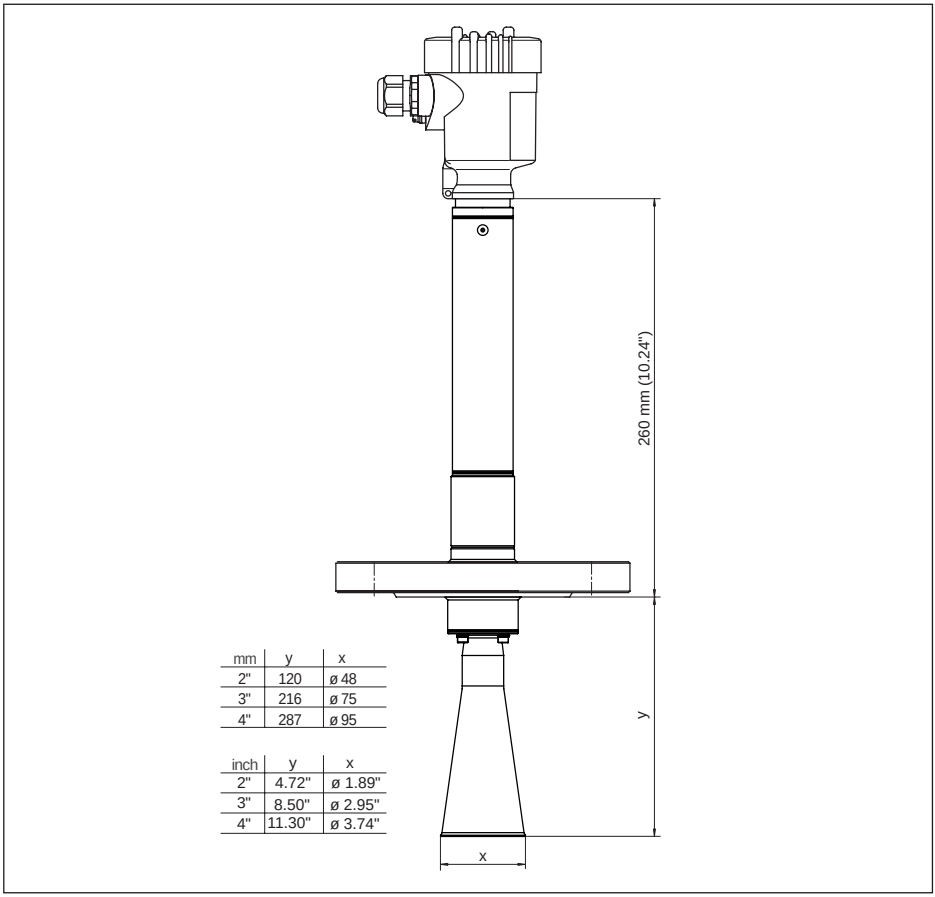

| mm | y | x |
|---|---|---|
| 1½" | 100 | ø40 |
| 2" | 120 | ø48 |
| 3" | 216 | ø75 |
| 4" | 430 | ø95 |

| inch | y | x |
|---|---|---|
| 1½" | 3.94" | ø1.58" |
| 2" | 4.72" | ø1.89" |
| 3" | 8.50" | ø2.95" |
| 4" | 16.93" | ø3.74" |

*Fig. 64: VEGAPULS 68, horn antenna in flange version*

*1 Standard*
*2 With temperature adapter up to 250 °C*

## VEGAPULS 68, horn antenna in flange version 450 °C

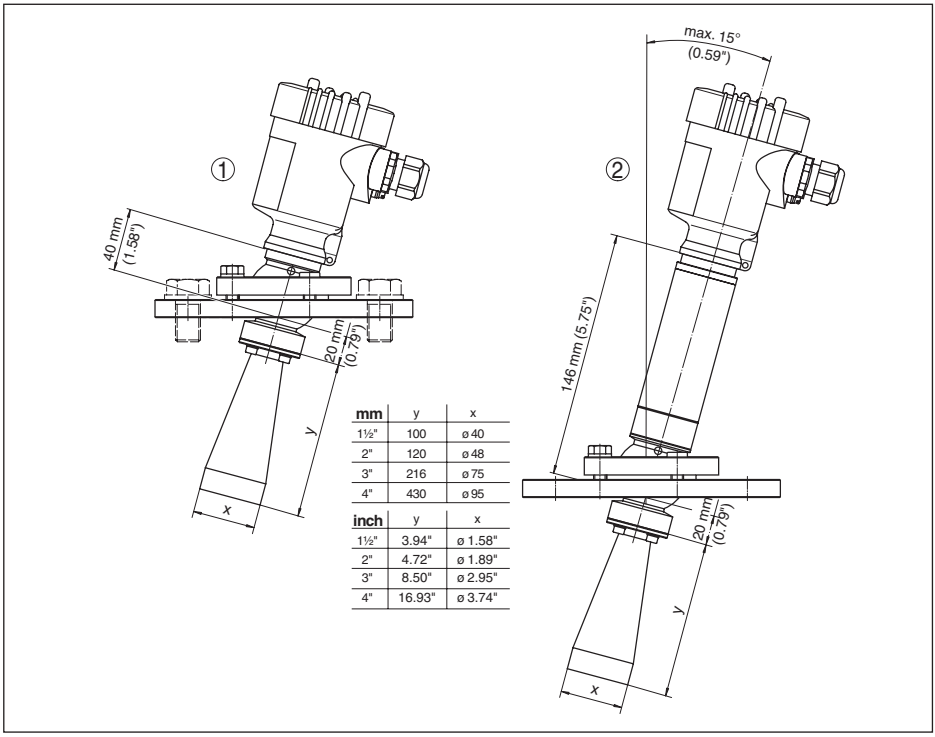



| mm | y | x |
|---|---|---|
| 2" | 120 | ø 48 |
| 3" | 216 | ø 75 |
| 4" | 287 | ø 95 |

| inch | y | x |
|---|---|---|
| 2" | 4.72" | ø 1.89" |
| 3" | 8.50" | ø 2.95" |
| 4" | 11.30" | ø 3.74" |

*Fig. 65: VEGAPULS 68, horn antenna in flange version with temperature adapter up to 450 °C*

## VEGAPULS 68, horn antenna and swivelling holder




| mm | y | x |
|---|---|---|
| 1½" | 100 | ø 40 |
| 2" | 120 | ø 48 |
| 3" | 216 | ø 75 |
| 4" | 430 | ø 95 |

| inch | y | x |
|---|---|---|
| 1½" | 3.94" | ø 1.58" |
| 2" | 4.72" | ø 1.89" |
| 3" | 8.50" | ø 2.95" |
| 4" | 16.93" | ø 3.74" |

*Fig. 66: VEGAPULS 68, horn antenna and swivelling holder*

*1 Standard*
*2 With temperature adapter up to 250 °C*

## VEGAPULS 68, horn antenna and swivelling holder, threaded fitting

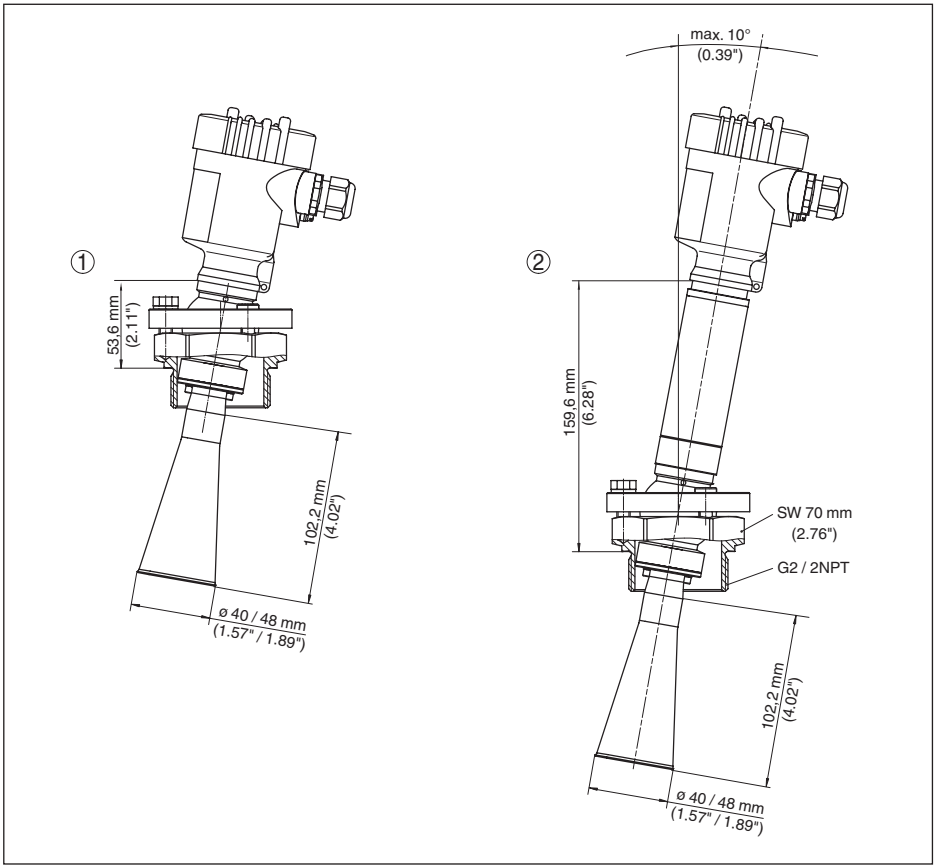



*Fig. 67: VEGAPULS 68, horn antenna and swivelling holder, threaded fitting*

*1 Standard*
*2 With temperature adapter up to 250 °C*

## VEGAPULS 68, parabolic antenna and swivelling holder

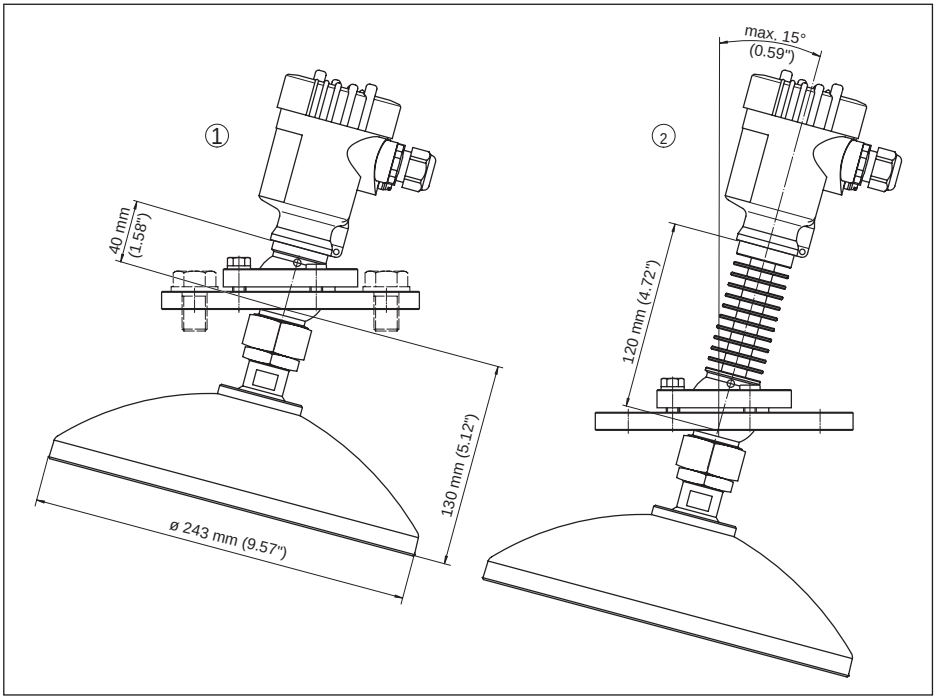



*Fig. 68: VEGAPULS 68, parabolic antenna and swivelling holder*

*1 Standard*
*2 With temperature adapter up to 200 °C*

## 11.4 Industrial property rights

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